

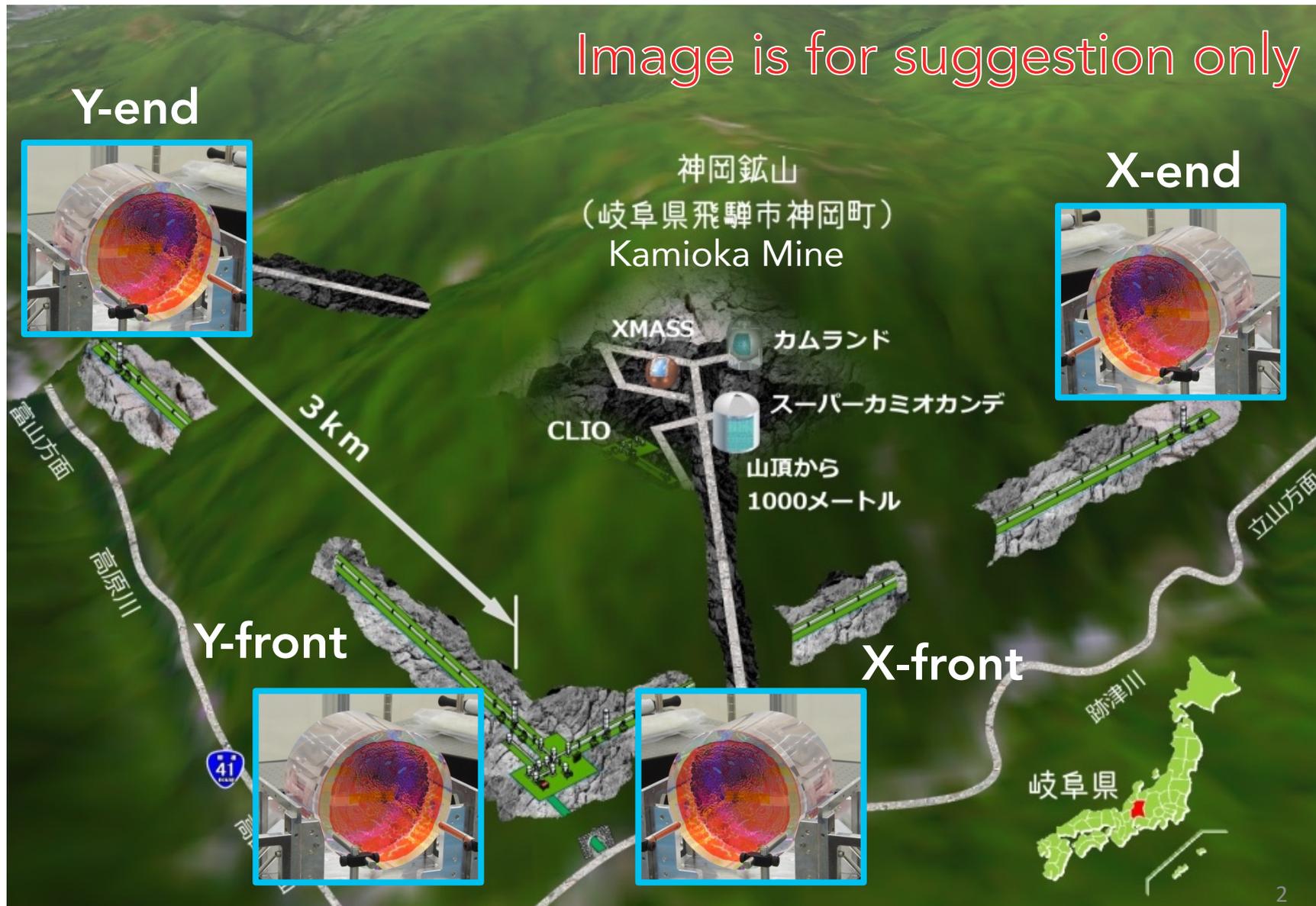


Conductive cooling of cryogenic payload in KAGRA

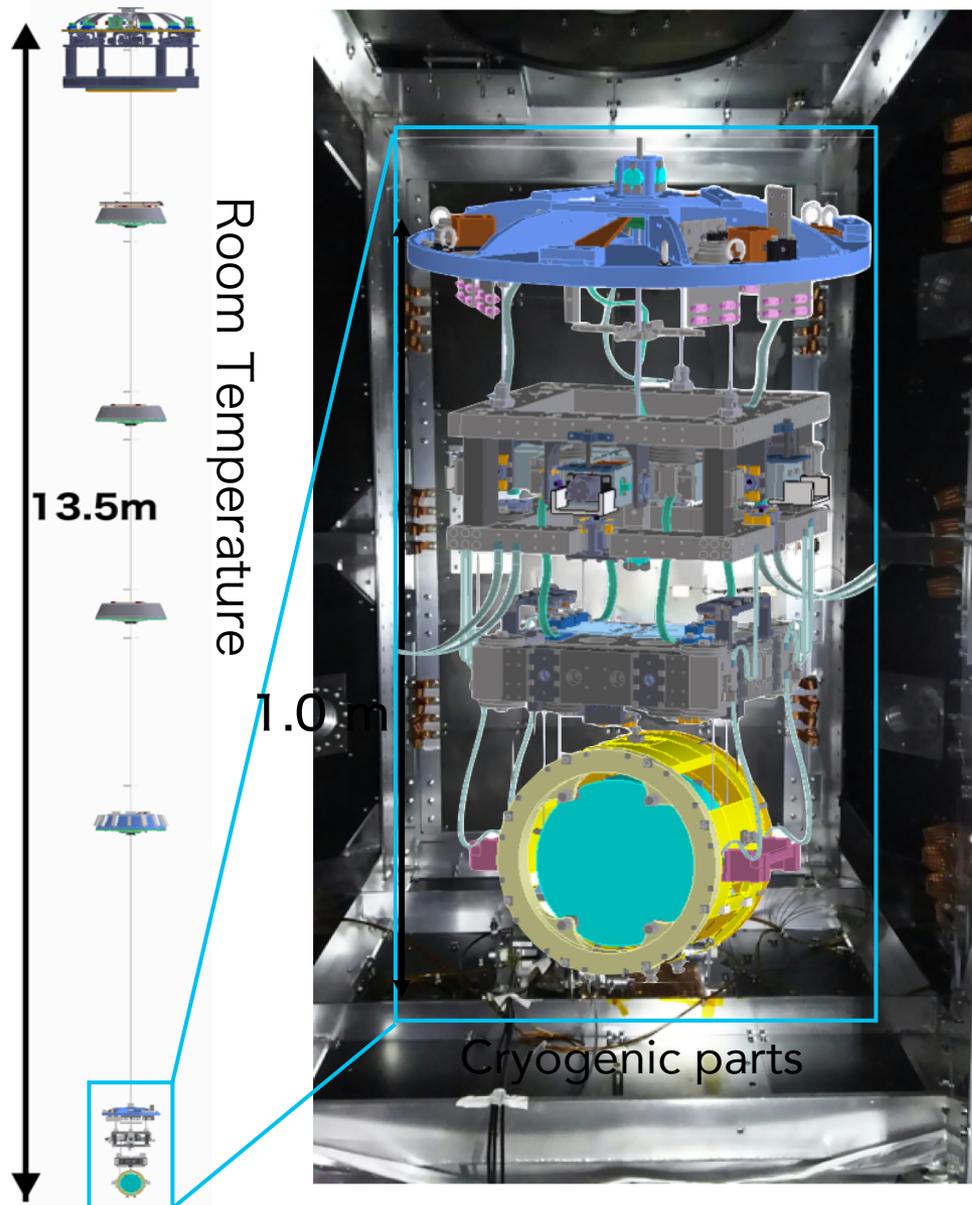
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ICRR, The Univ. of Tokyo
Cryogenics Group

Cryogenic mirror in KAGRA

Image is for suggestion only



Cooling of payload



- To be quiet

➔ Radiative Cooling

$$\frac{dT_{\text{pay}}}{dt} = A\varepsilon\sigma(T_{\text{pay}}^4 - T_{\text{shield}}^4)$$

- Powerful at high temp.
- Ineffective at low temp.

- To be rapid

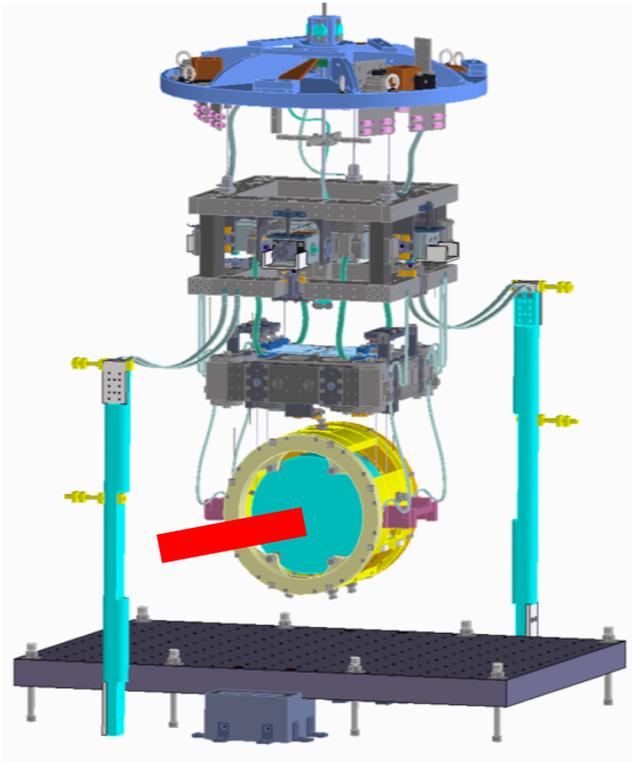
-> Effective radiative cooling with black coating

-> Conductive cooling

➔ High thermal conductive heat-links

Role and Concern of heat-links

Heat-links connect the payload and cooling bars(cryocoolers).



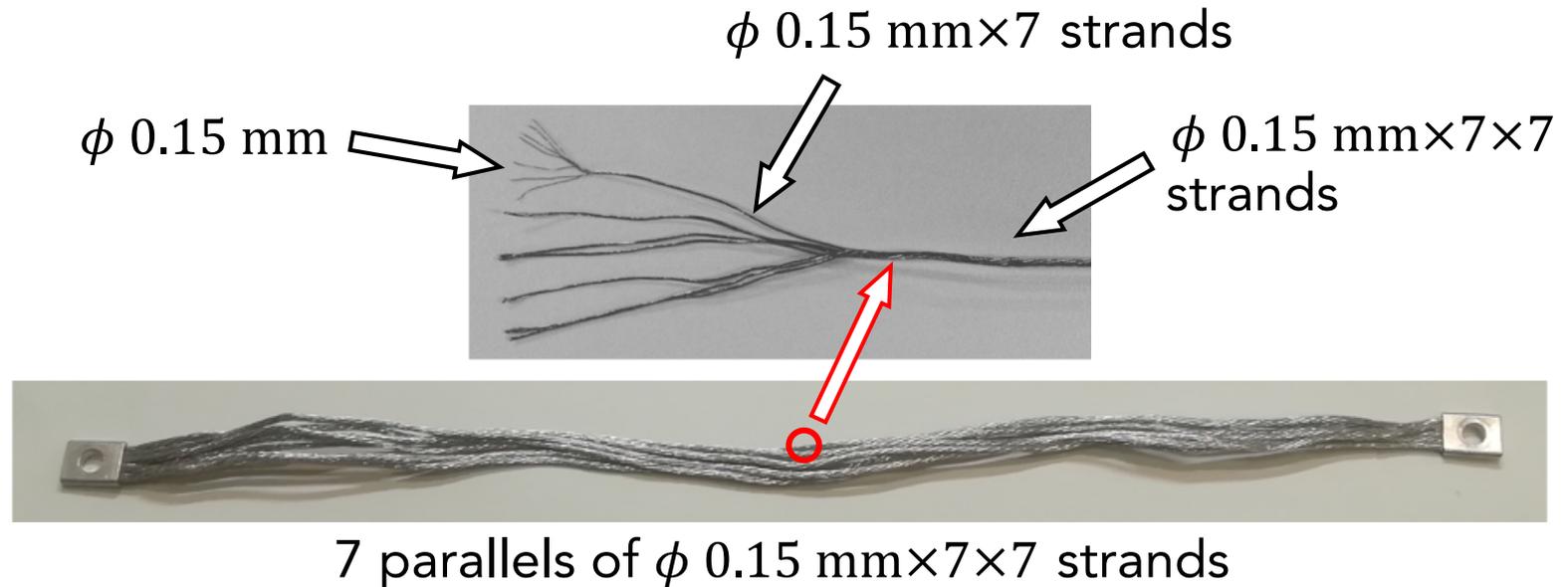
- Role = Heat extraction
Heat-links must extract heat inputted to the mirror. We cannot disconnect them even during operation.
- Concern = Vibration via heat-links
Heat-links may introduce vibration to the payload from cooling bars.

Heat-links must be **high thermal conductive and flexible** as much as possible.

KAGRA heat-links

- Ultra high-purity aluminum heat-links

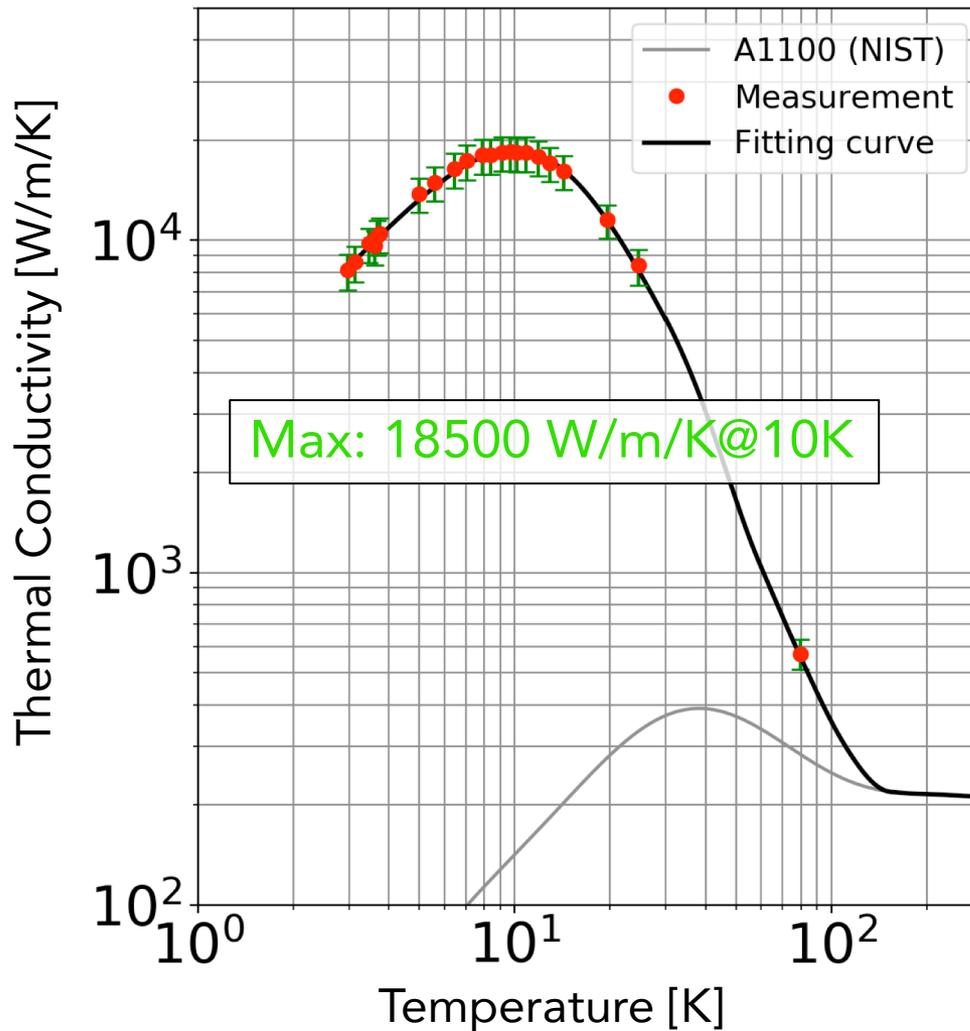
Purity: 99.9999%, 6N (Sumitomo Chemical Co., Ltd.)



high thermal conductivity and
low spring constant(stiffness)

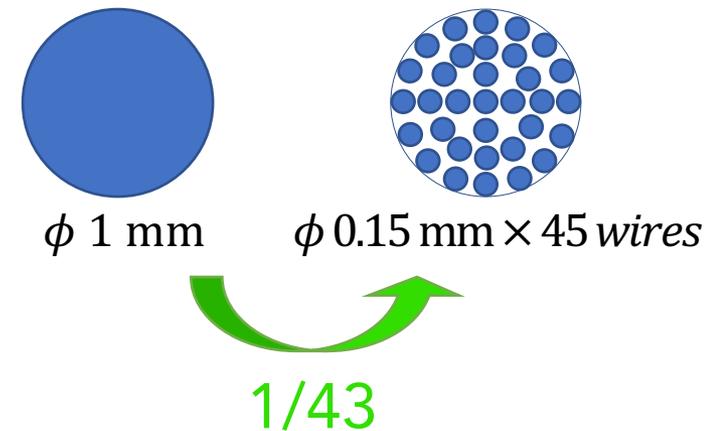
Measured Data

Thermal Conductivity



Spring Constant

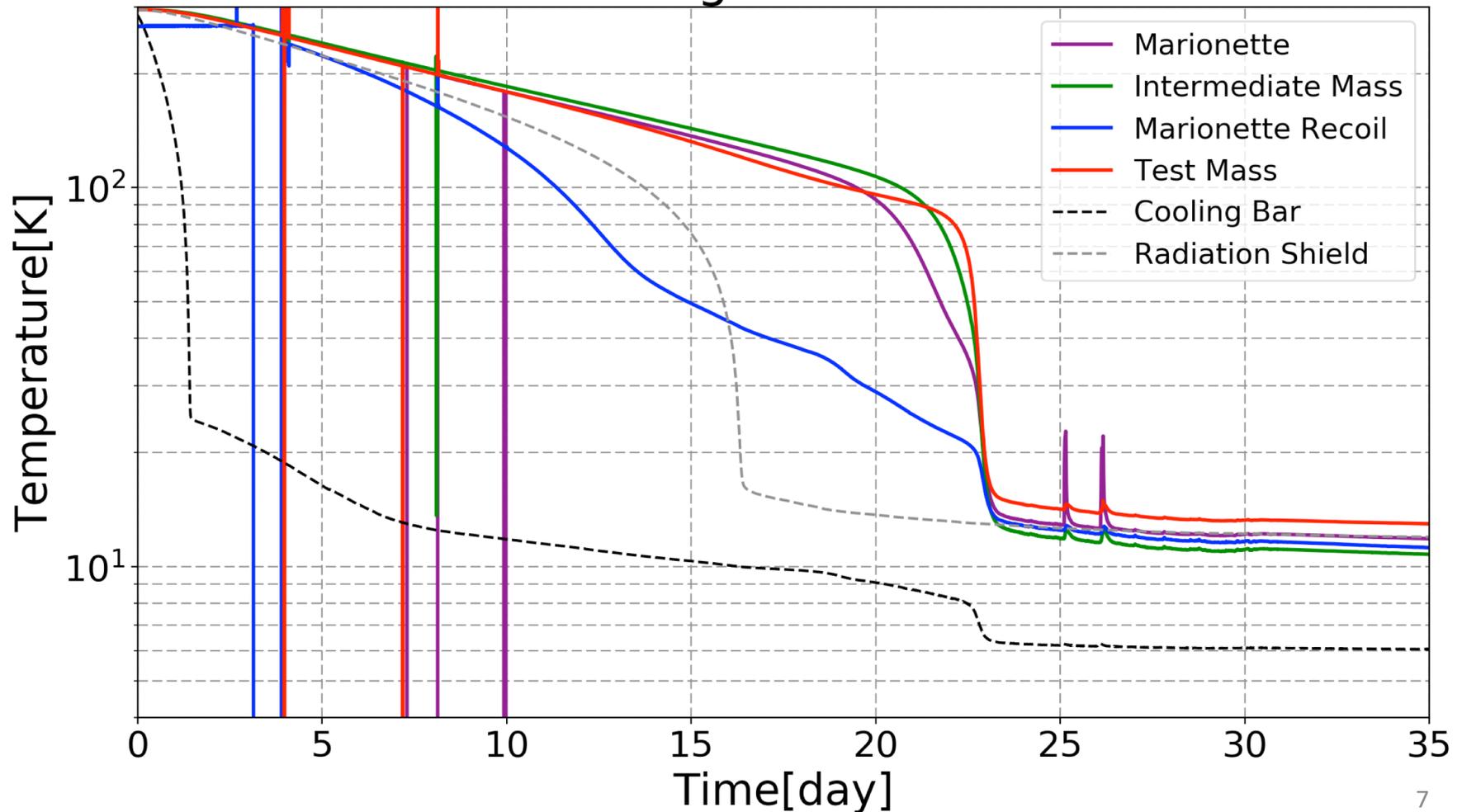
- Spring constant is an index of the stiffness.
- We compared it between single thick wire and our heat-links which are both same cross-sectional area.



How powerful heat-links are.

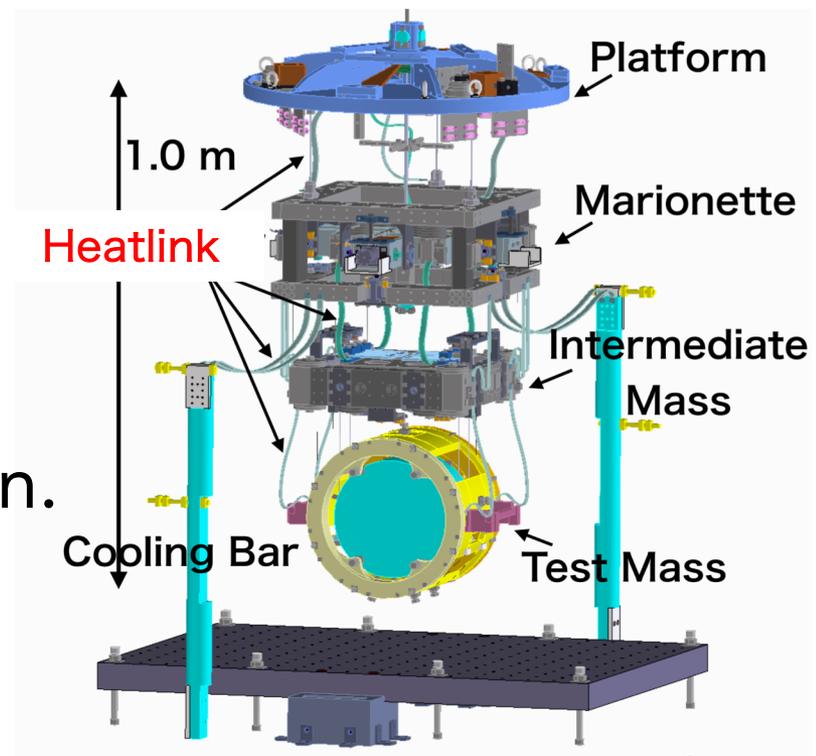
Test cooling of payload in 2017 summer

Cooling Test Result

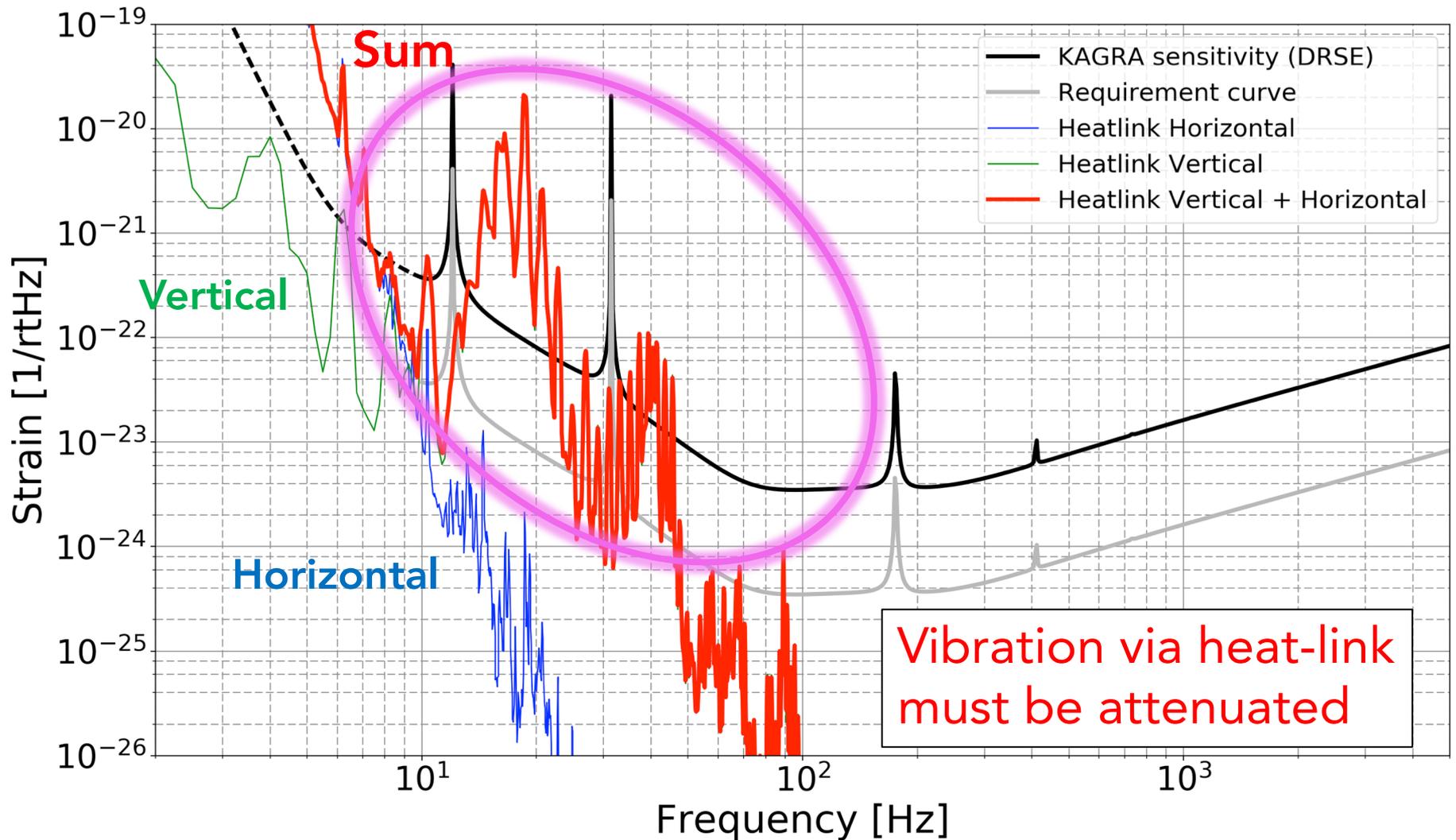


Vibration through heat-links

- Heatlinks are absolutely necessary to reach 20 K for mirror.
- However, Marionette Recoil Mass, which is connected heatlinks from **cooling bars**, is already suspended by Type-A and Platform stage.
- We calculated vibration transmission via heatlinks in the case of direct connection.

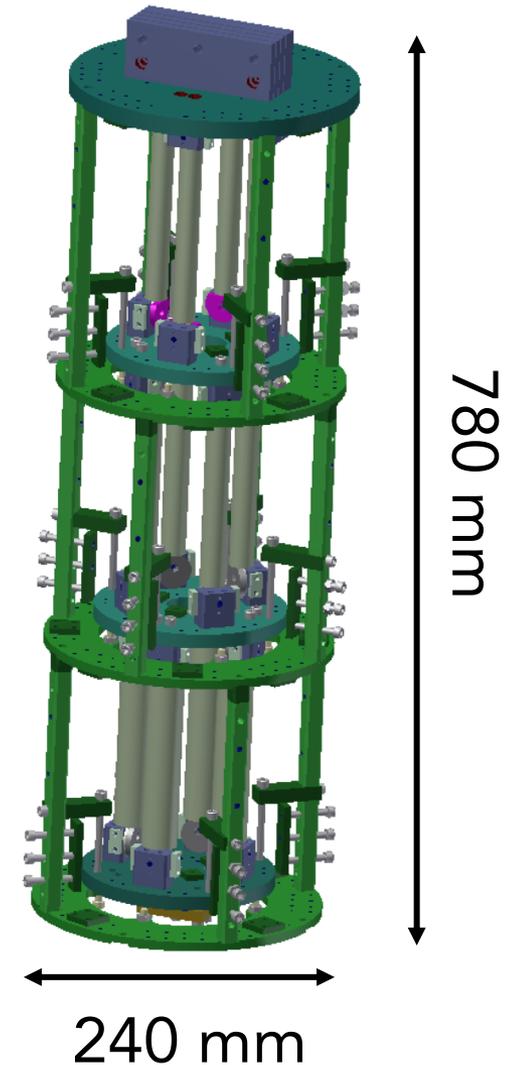
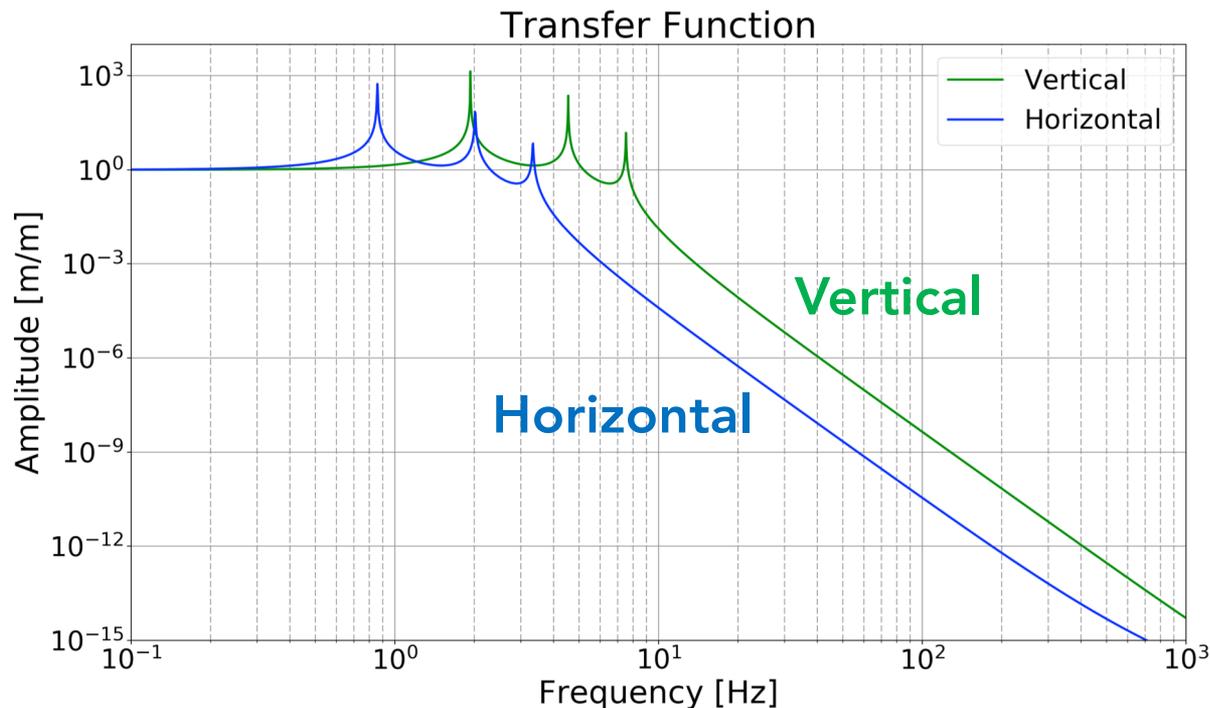


Comparison with KAGRA sensitivity

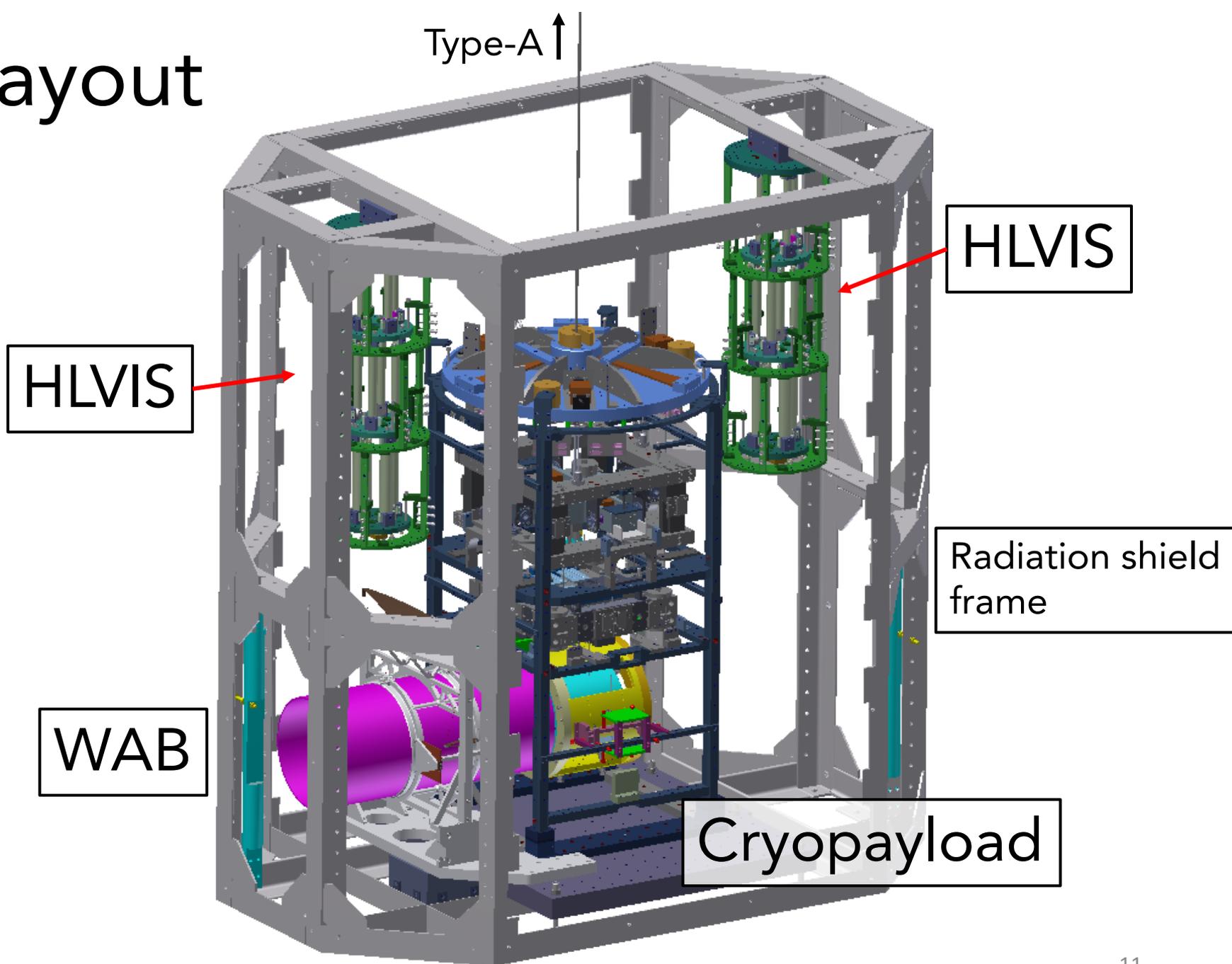


HLVIS design

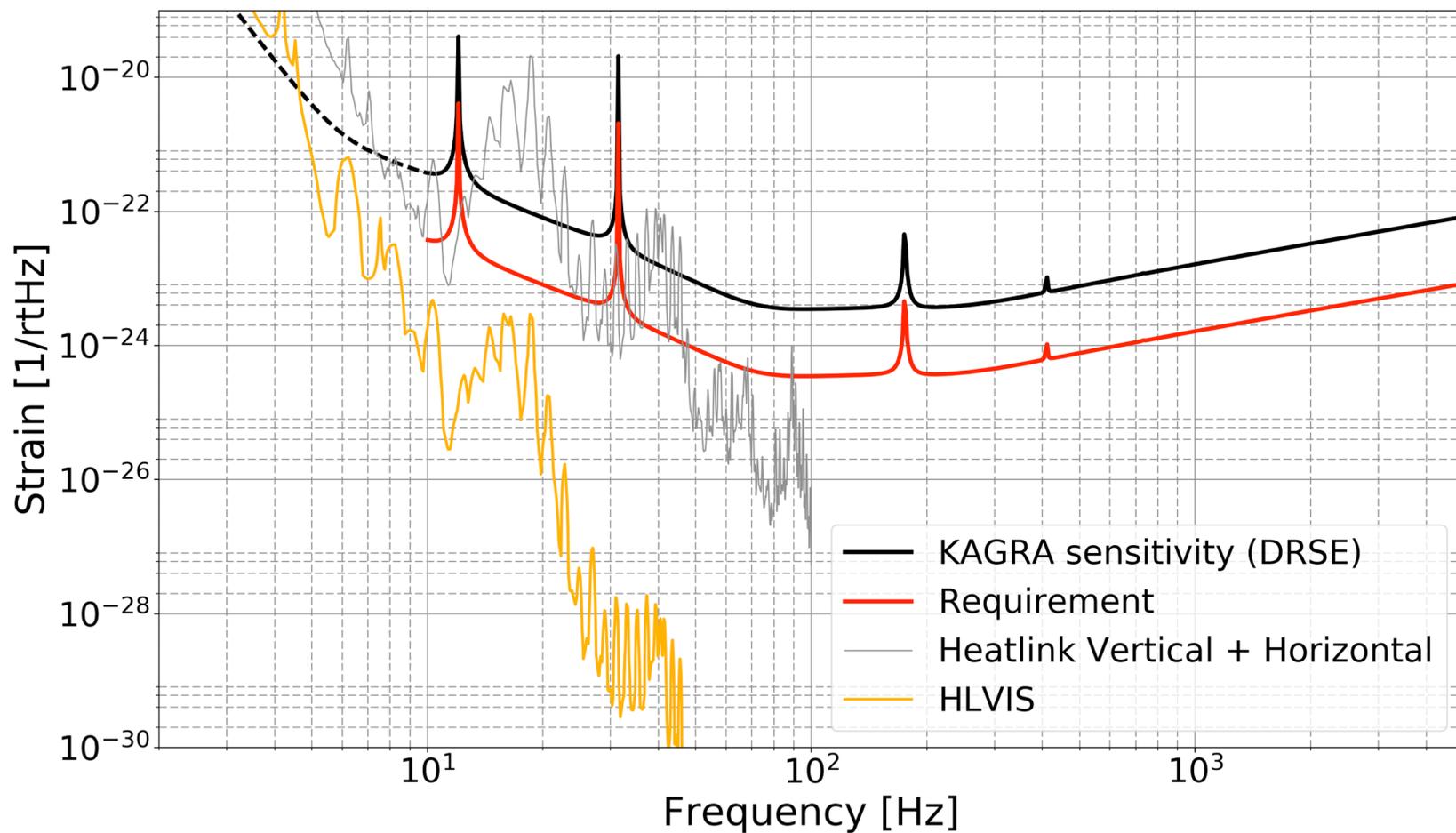
- 3 Hz - 3 stages
- 4 tension springs for each stage (2 R-handed, 2 L-handed)
- Total mass 20 kg



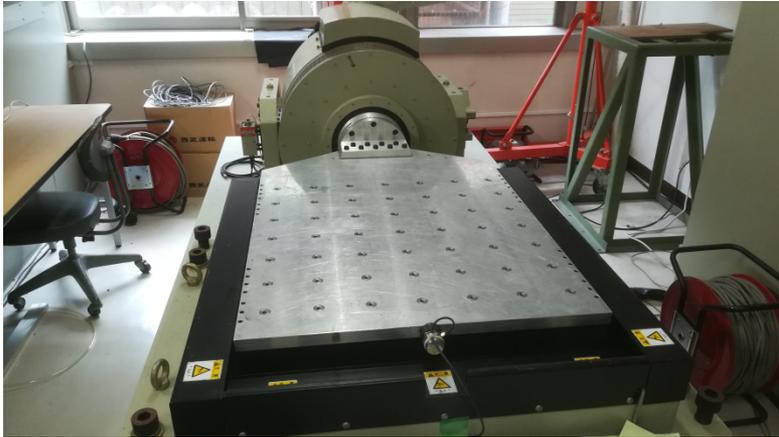
Layout



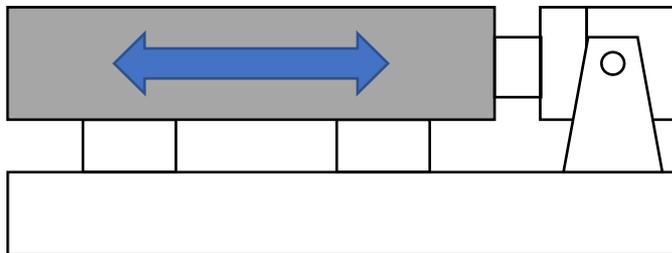
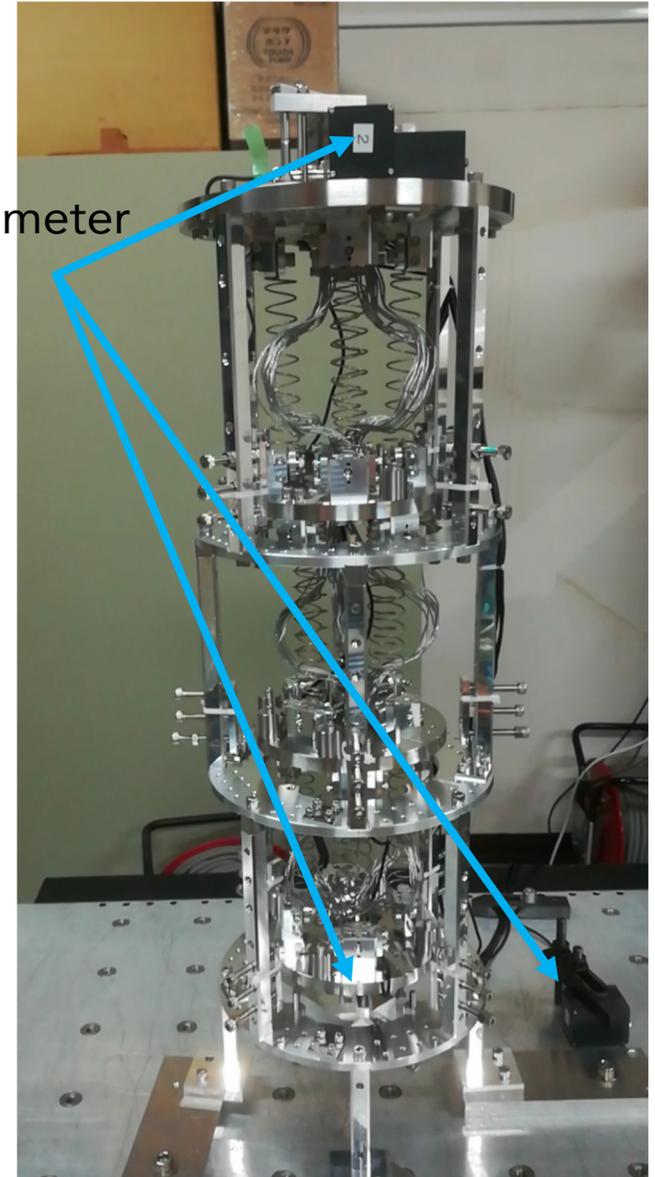
Attenuation of vibration transmission = Design performance



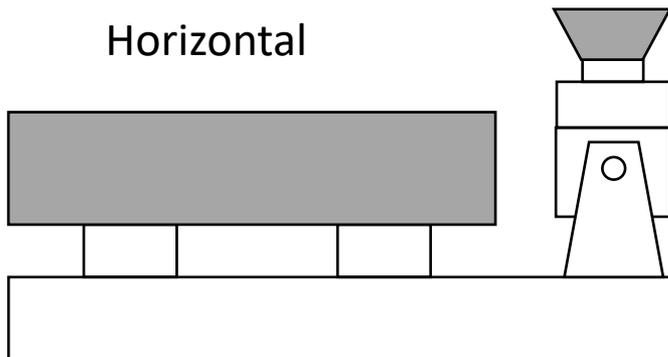
Shaking test at ERI



Accelerometer

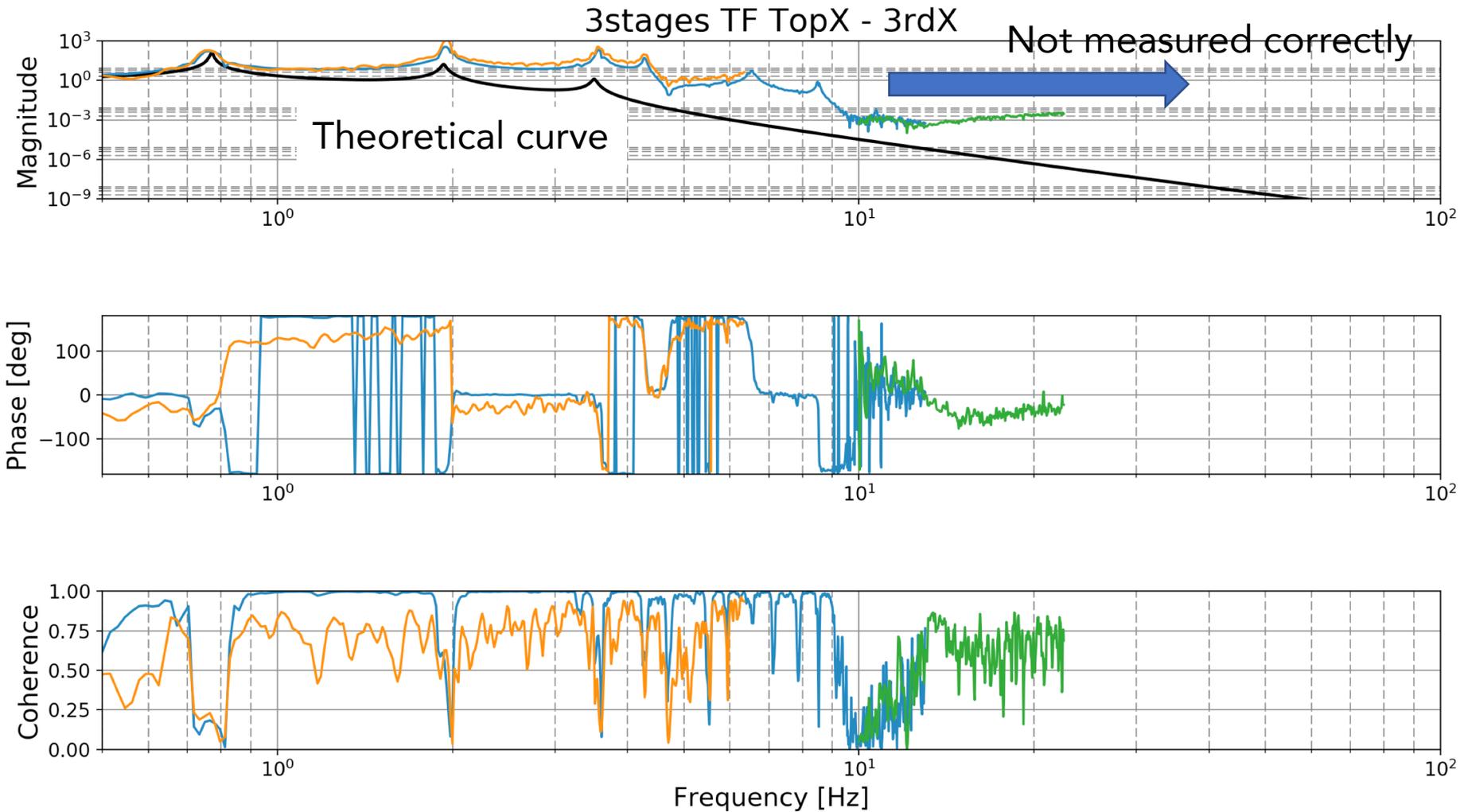


Horizontal

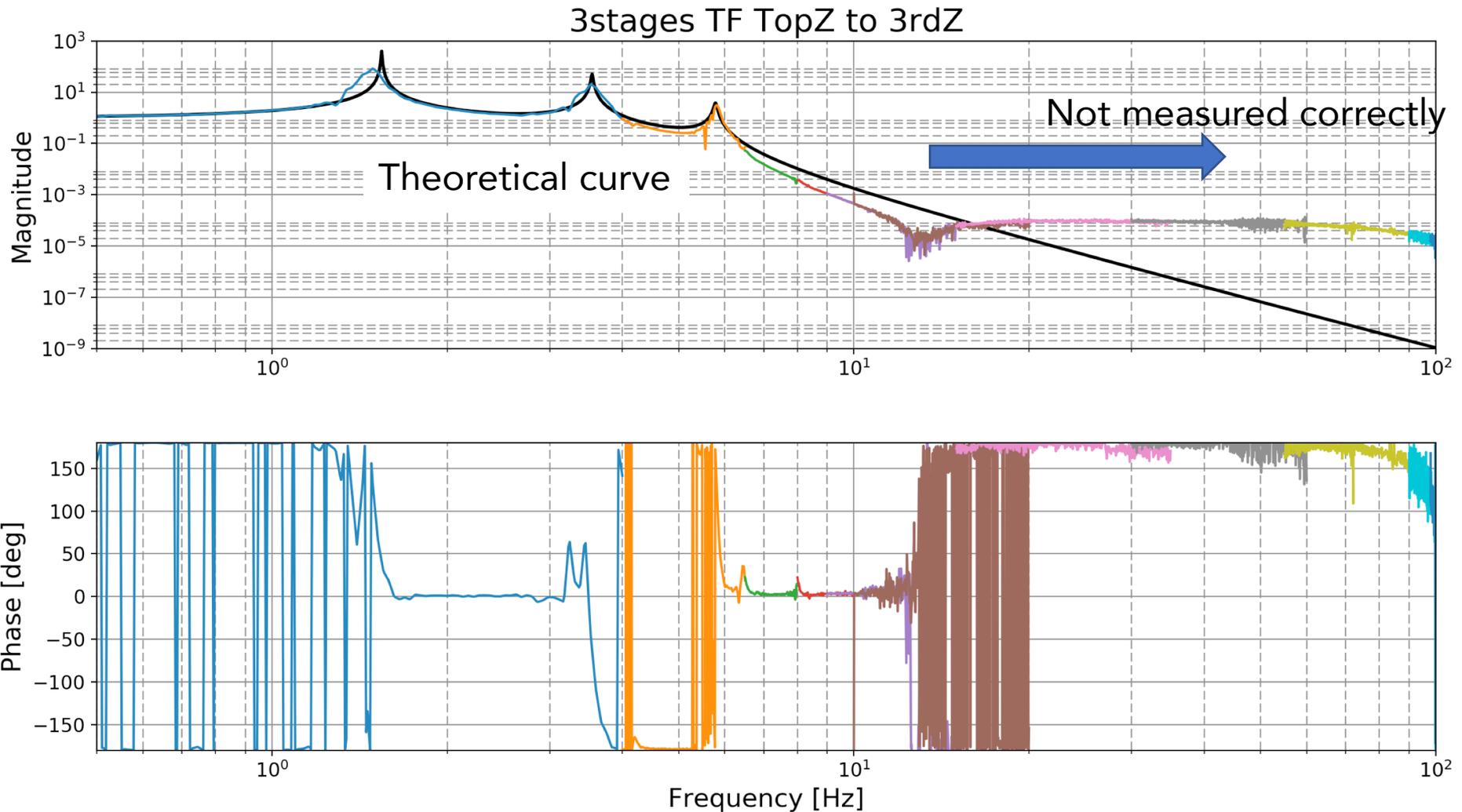


Vertical

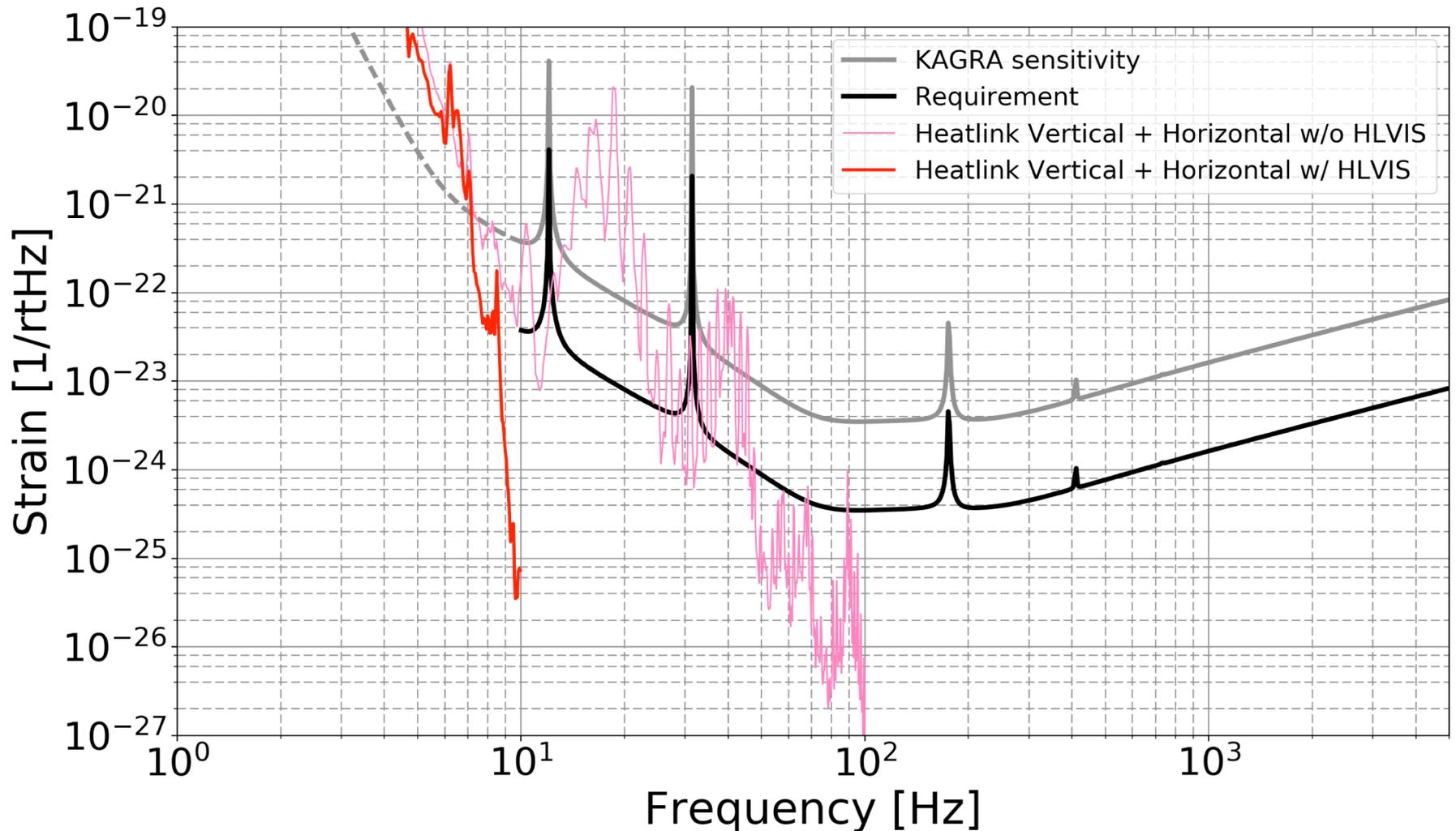
Transfer function: Horizontal



Transfer function: Vertical

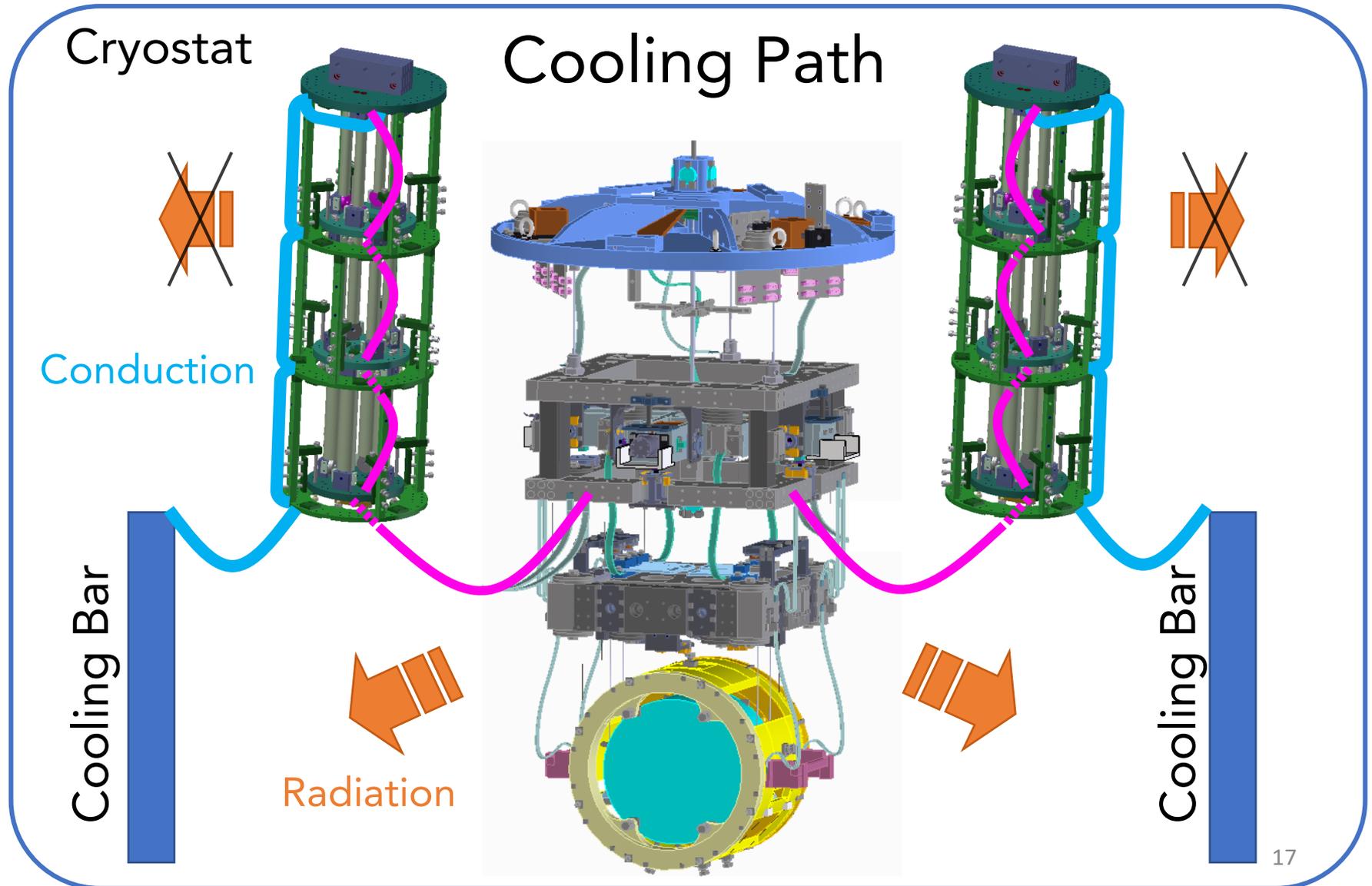


Estimated vibration level below 10 Hz employing measured TFs



Cooling time calculation

- Rigid 6N Al plate
- Soft heat-links

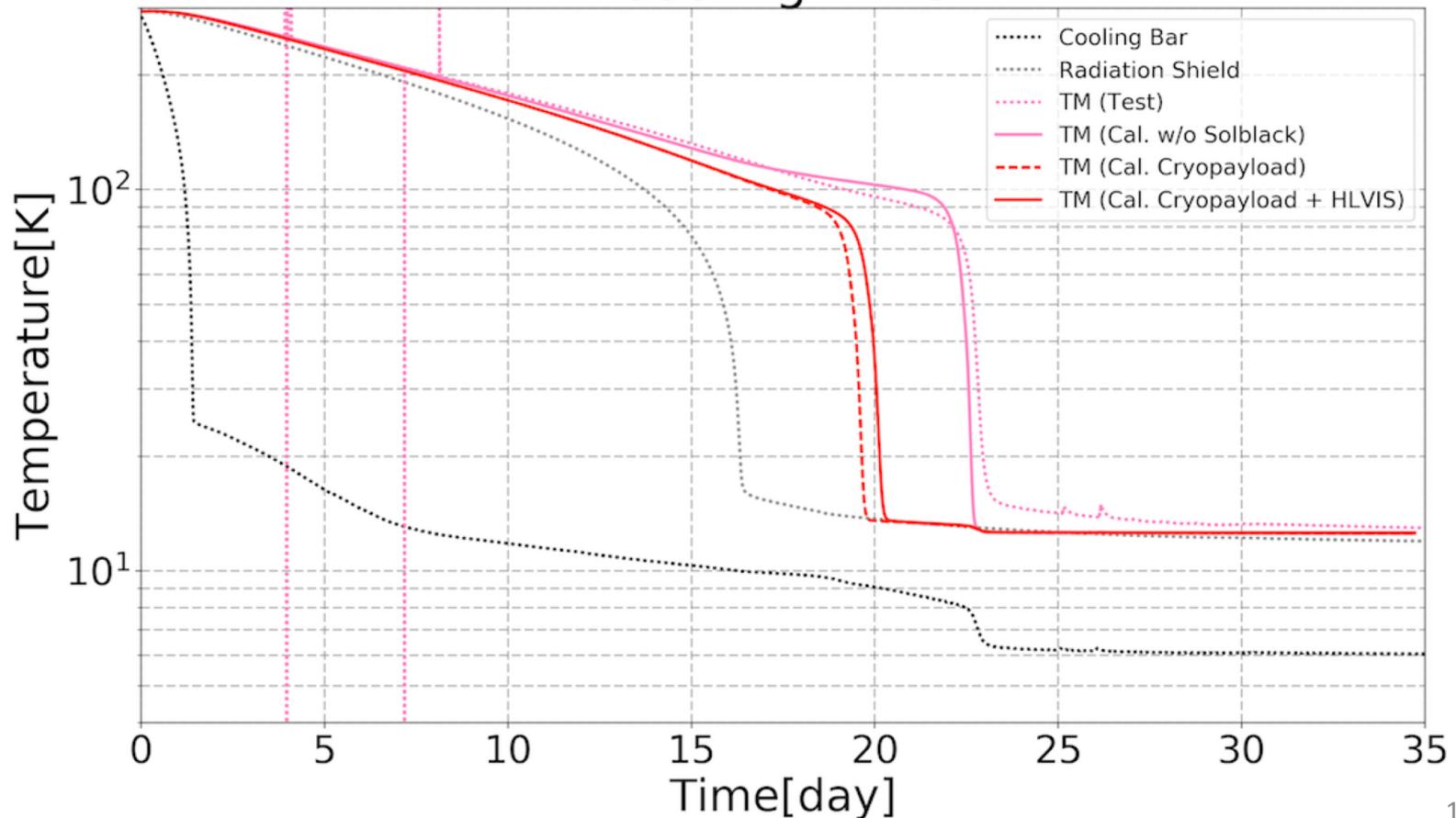


Cooling time of TM:

Cryopayload only

- Cooling test result • Calculation w/ Solblack - - - - -
- Calculation w/o Solblack — — — — — • Cryopayload + HLVIS w/ Solblack — — — — —

Cooling Time

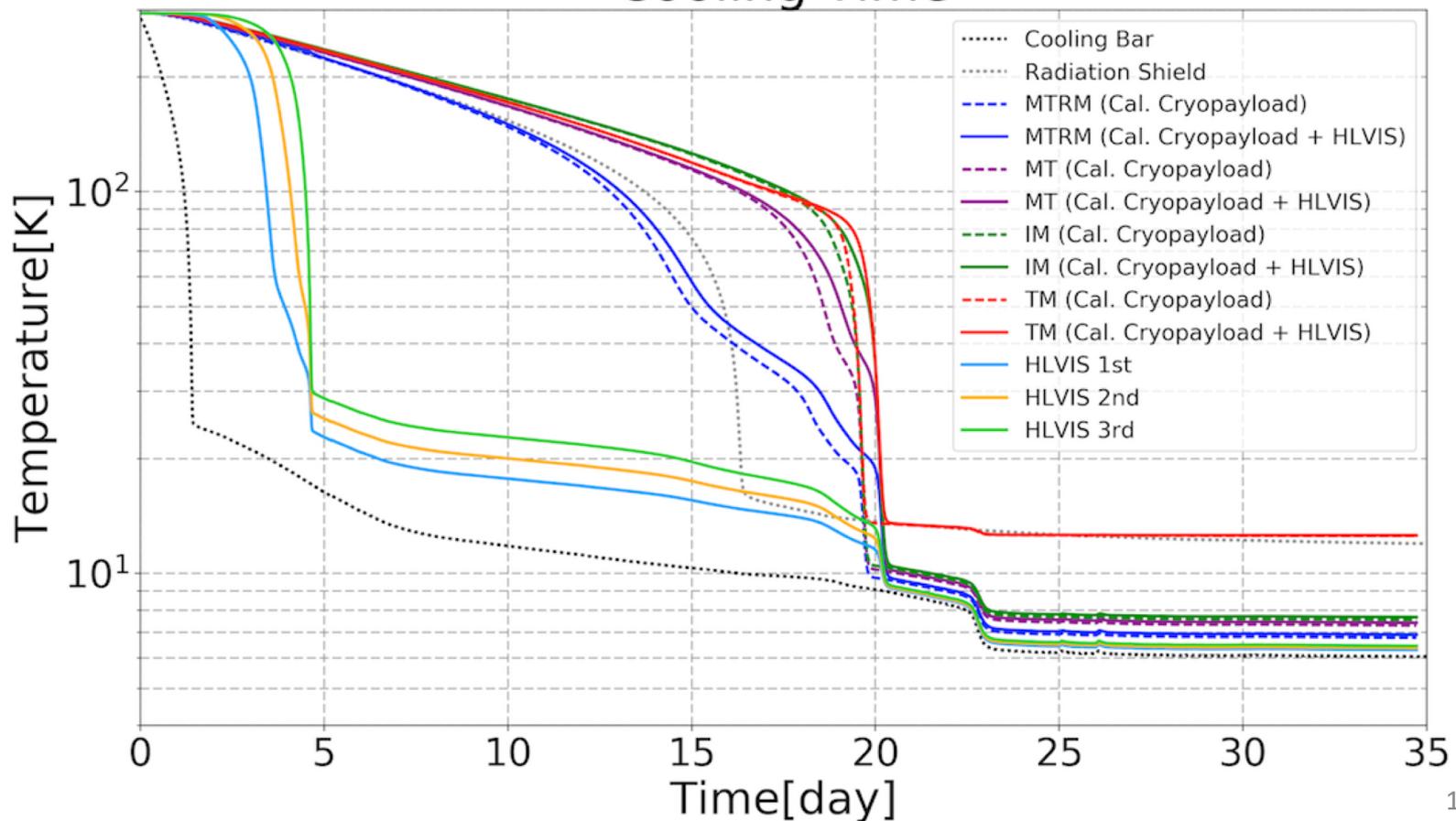


Cooling time: HLVIS & Cryopayload

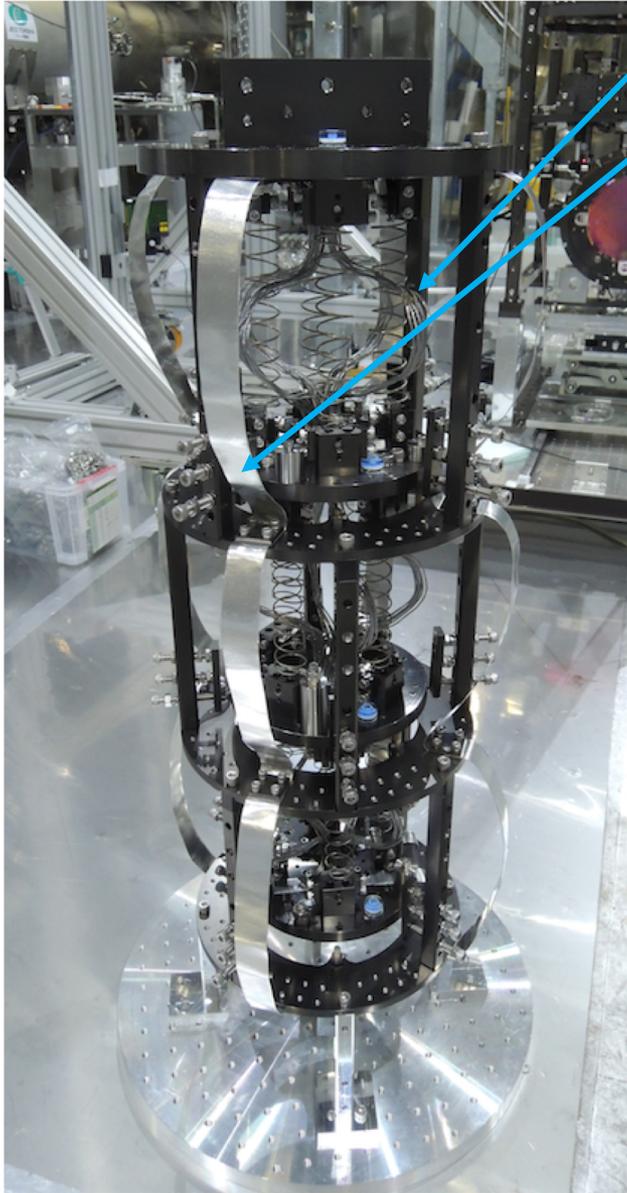
Cryopayload only

- Cooling test result • Calculation w/ Solblack - - - - -
- Calculation w/o Solblack — — — — — • Cryopayload + HLVIS w/ Solblack — — — — —

Cooling Time



Assembly of HLVIS



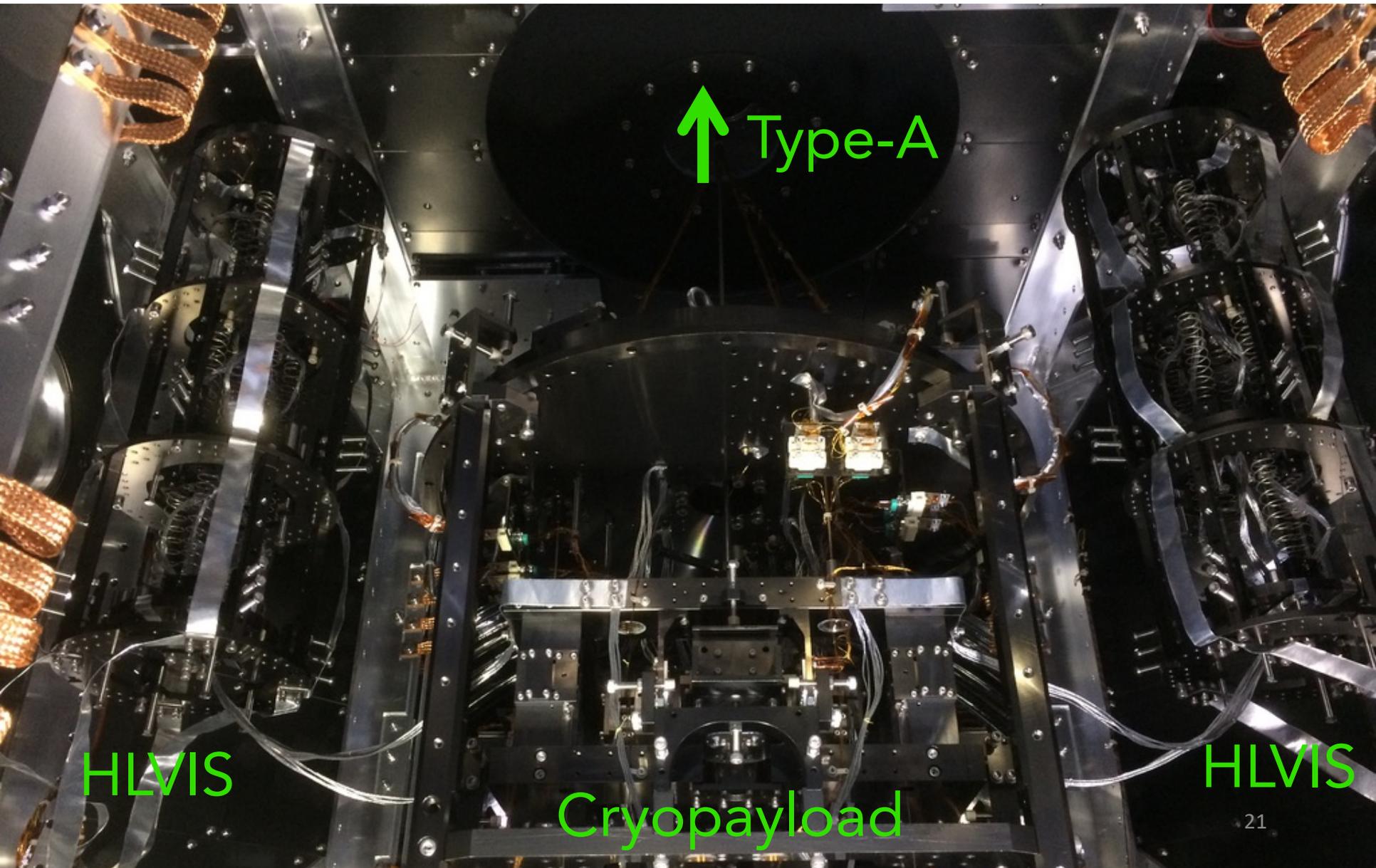
Heat-links

6N Aluminum thin band



All the HLVISs in total have been installed into each cryostat.

Best Family in the Cryostat



↑ Type-A

HLVIS

Cryopayload

HLVIS

Summary

- We developed high thermal conductive and flexible heat-links.
- We concern about vibration transmission via heat-links.
- Heatlink-Vibration-Isolation System was developed to attenuate those vibration.
- Transfer functions of HLVIS were measured below 10 Hz at ERI.
- Cooling time considering HLVIS was calculated. HLVIS doesn't affect cooling time so much.
- *Transfer function above 10 Hz will be measured soon in KEK.*
- *HLVIS TF must be included in the Type-A suspension control.*

End