Contribution ID: **12**   Type: **not specified**

Robots for GW detectors and infrastructure monitoring and operation: Can Networks of Autonomous Robotics Vehicles help the characterization of Newtonian, Acoustic and Other Source Noise in GW detection?

Tuesday, 15 January 2019 09:45 (30 minutes)

Presenter: Prof. BONSIGNORIO, Fabio (Scuola Superiore Sant'Anna)

Session Classification: ML for low-frequency seismic measurement