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Robots for GW detectors and infrastructure monitoring and operation: Can Networks of Autonomous Robotics Vehicles help the characterization of Newtonian, Acoustic and Other Source Noise in GW detection?

Tuesday, January 15, 2019 9:45 AM (30 minutes)

Presenter: Prof. BONSIGNORIO, Fabio (Scuola Superiore Sant'Anna)

Session Classification: ML for low-frequency seismic measurement