1st Conference on Machine Learning for Gravitational Waves, Geophysics, Robotics, Control System and CA17137 MC2 meeting



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## Robots for GW detectors and infrastructure monitoring and operation: Can Networks of Autonomous Robotics Vehicles help the characterization of Newtonian, Acoustic and Other Source Noise in GW detection?

Tuesday, 15 January 2019 09:45 (30 minutes)

**Presenter:** Prof. BONSIGNORIO, Fabio (Scuola Superiore Sant'Anna)

Session Classification: ML for low-frequency seismic measurement