

ET's Nullstream

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What are the uses of a nullstream?

- 1) Estimation of instrument-noise PSD
- 2) Detector calibration
- 3) GW detection in the presence of non-Gaussian noise
- 4) CBC parameter estimation (?)
- 5) Stochastic searches

ET Nullstream vs Network Nullstream

- 1) ET nullstream (in contrast to a network nullstream)
 - a) also works in the simultaneous presence of many GW signals;
 - b) is not affected by changing source directions (like in the case of BNS observations due to Earth rotation).
- 2) Dependence of network nullstream on source-direction estimates poses a significant limitation (e.g., see glitch vetoing slide)

Estimation of PSD of Instrument Noise

Binary neutron stars (800,000 mergers per year)

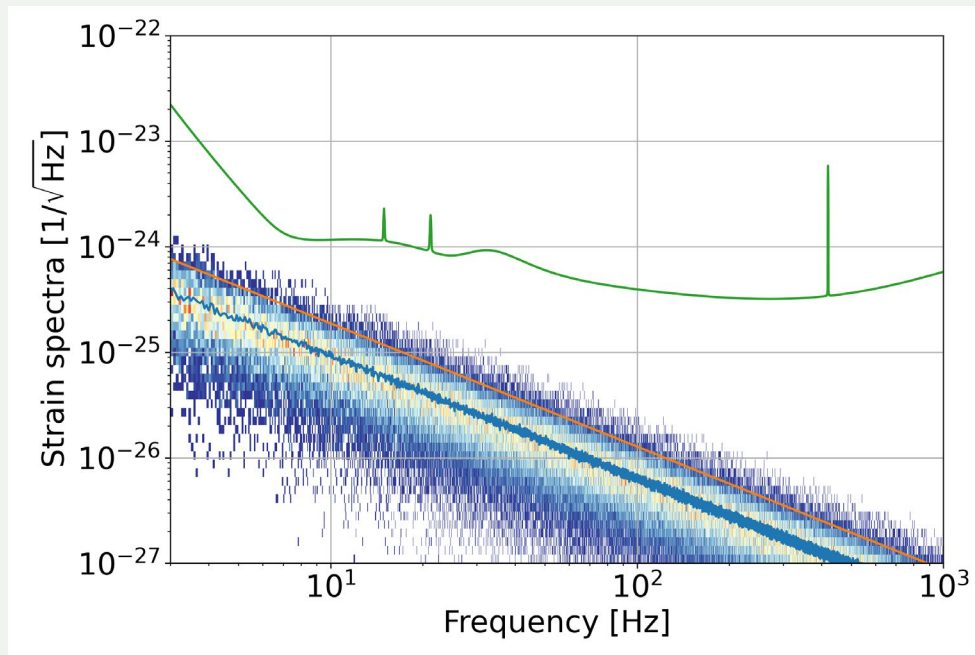
Time segment	Number of BNS contributing energy above 2Hz
1 minute	100
10 minutes	300
1 hour	500
4 hours	800
24 hours	2500

Binary black holes (100,000 mergers per year)

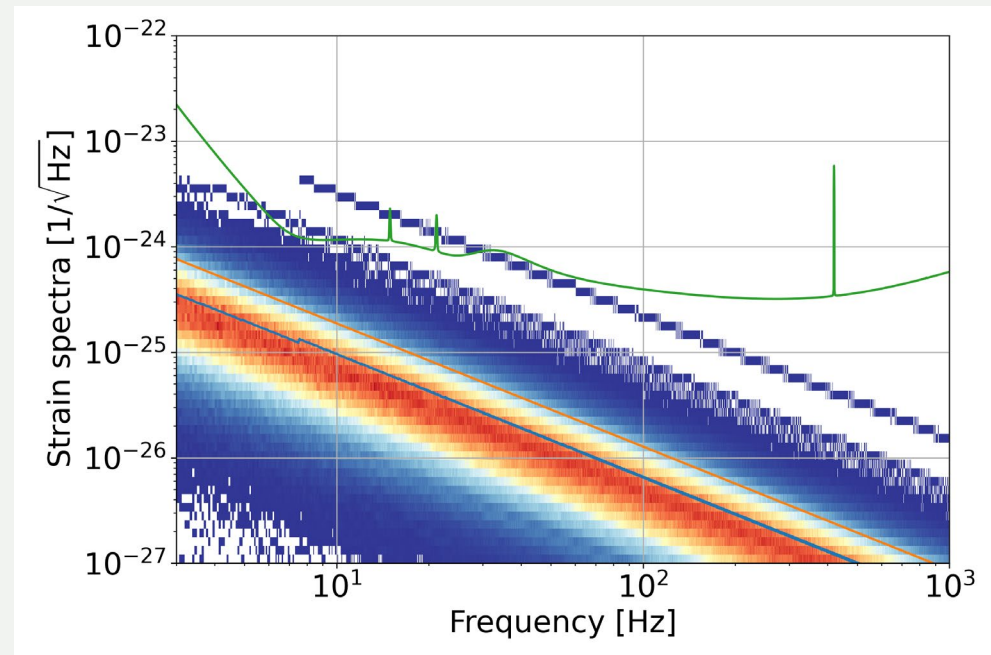
Time segment	Number of BBH contributing energy above 2Hz
1 minute	2
24 hours	300

Astrophysical Foreground: BNS

24 hours PSD/FFT time
100 PSDs forming histogram



1 min PSD/FFT time
7200 PSDs forming histogram

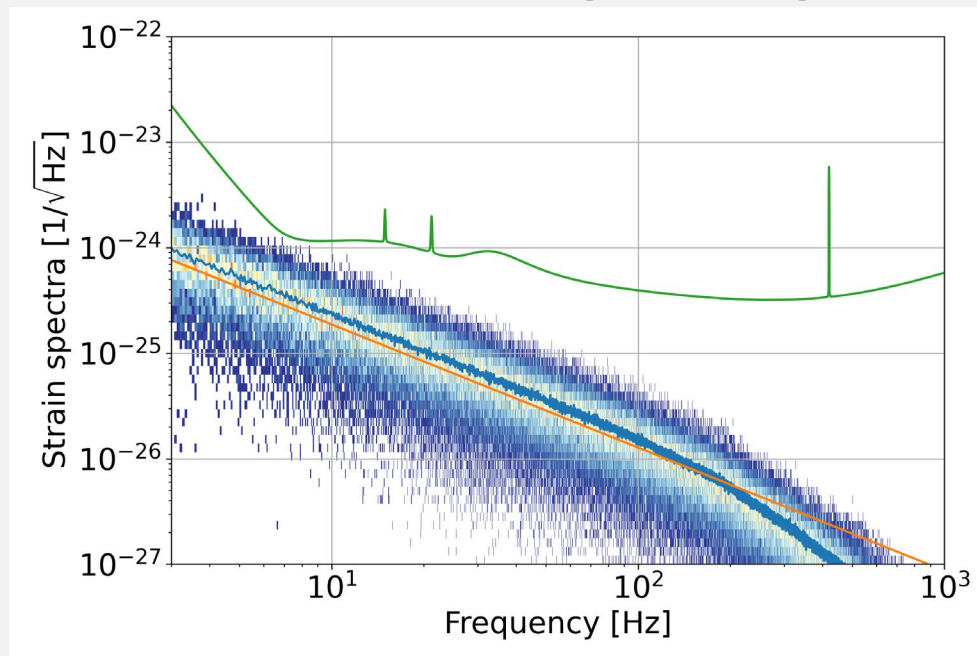


It seems that there is no significant impact of BNS foreground on estimates of instrument-noise PSDs.

Astrophysical Foreground: BBH

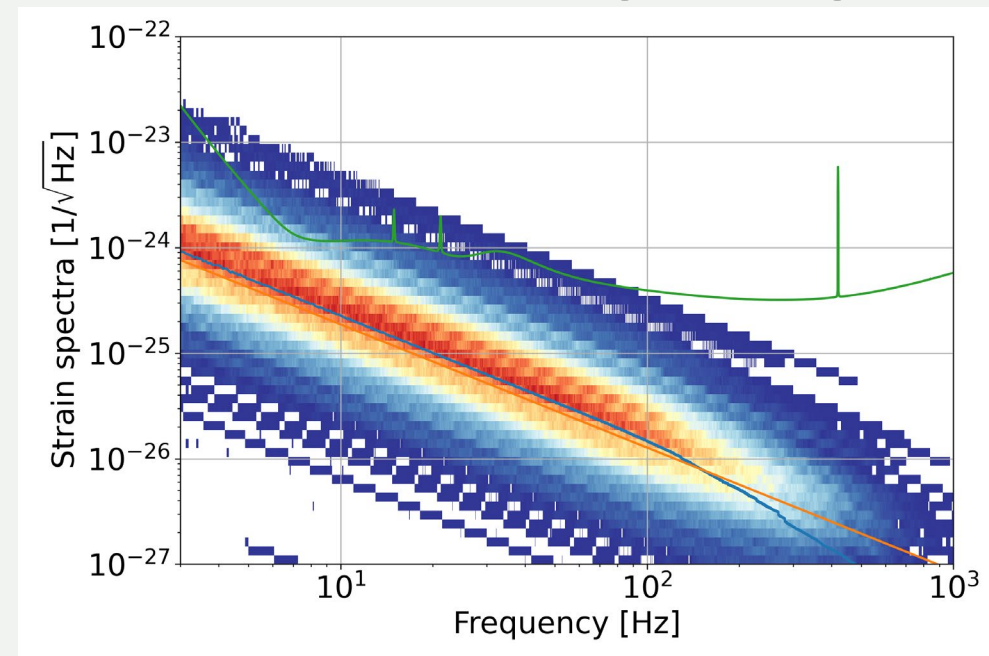
24 hours PSD/FFT time

100 PSDs forming histogram



1 min PSD/FFT time

7200 PSDs forming histogram



BBH signals can be expected to significantly perturb estimates of instrument-noise PSDs.

ET Nullstream for PSD Estimates

Data from $k=1,2,3$ ET components as sum of GW signal and noise

$$d_k(t) = s_k(t) + n_k(t)$$

Definition of nullstream

$$N(t) = d_1(t) + d_2(t) + d_3(t) = n_1(t) + n_2(t) + n_3(t)$$

Instrument noise PSD obtained as cross-correlation with nullstream

$$\langle n_k | n_k \rangle = \langle d_k | N \rangle$$

Detector Calibration

Self-calibration of Networks of Gravitational Wave Detectors

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Basic idea: construct matched filter to detect residuals of GW signals in the nullstream. The filter provides information about calibration errors.

Calibration errors

Required for network nullstreams

$$\tilde{N}^{123} = \tilde{N}_n^{123} + \sum_a A^{(a)} c^{(a)}(f) [F_+^{(a)} \tilde{h}_+(f) + F_\times^{(a)} \tilde{h}_\times(f)] e^{2\pi i f \tau^a}$$

- 1) Nullstream residuals are low SNR (since calibration errors are small). So, one needs to combine analyses of many CBC signals to obtain useful information about calibration errors.
- 2) Absolute calibration can in principle be achieved with one detector being accurately calibrated at one frequency, or with accurate source-distance estimates, e.g., from EM counterparts.

Optimal GW Searches Using the Nullstream

- 1) With nullstream, it is in principle sufficient to see the GW signal in only one detector (instead of requiring coincident detections).
- 2) Reject transients if they appear in the nullstream. ET superior to 3-detector network: since the nullstream does not depend on GW direction, weaker glitches can be vetoed.
- 3) In ET, efficiency of glitch veto limited by calibration errors (calibration errors can cause glitches not to be vetoed).

Coherent network analysis technique for discriminating gravitational-wave bursts from instrumental noise

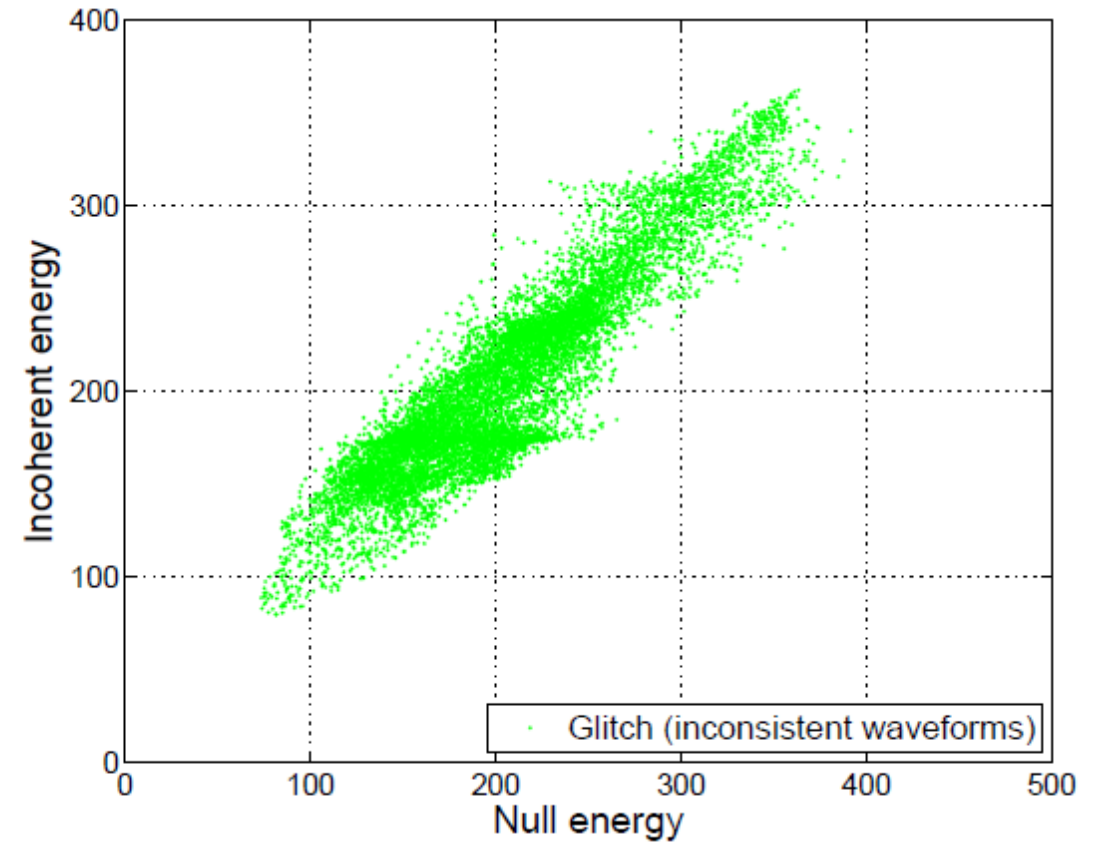
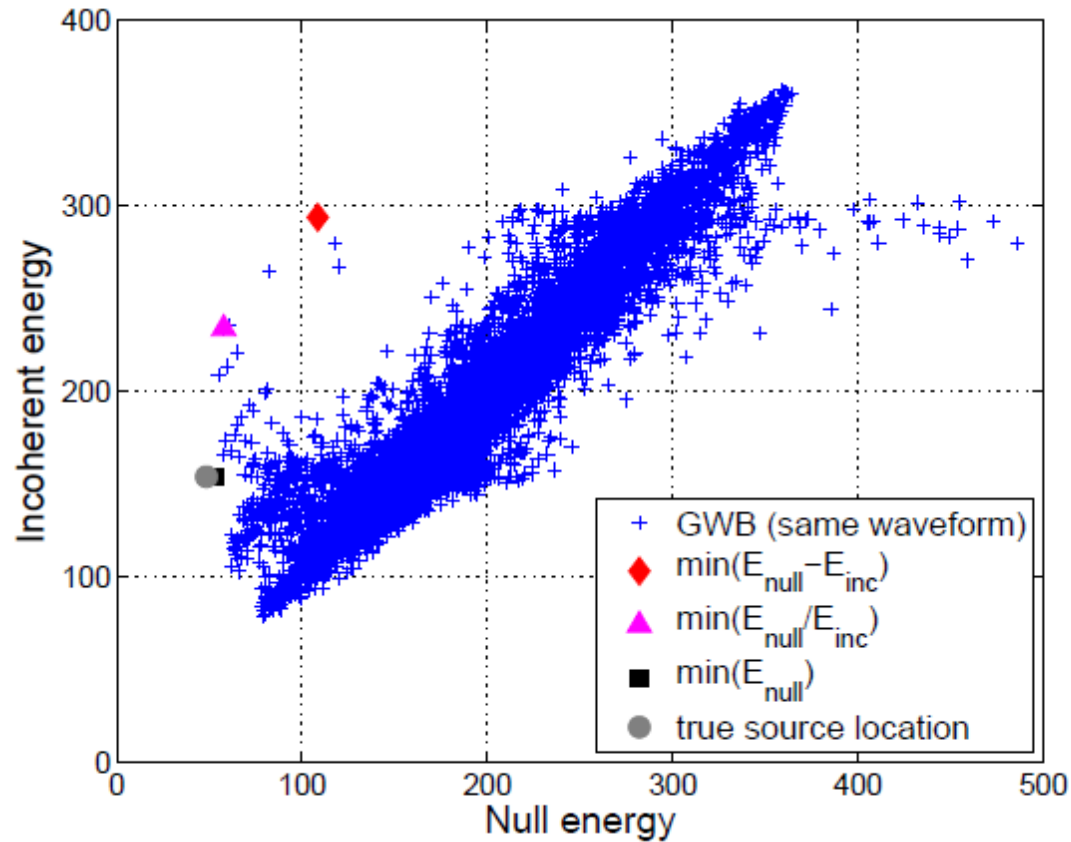
Shourov Chatterji, Albert Lazzarini, Leo Stein, and Patrick J. Sutton
LIGO - California Institute of Technology, Pasadena, CA 91125

Antony Searle
Australian National University, Canberra, ACT 0200, Australia

Massimo Tinto
Jet Propulsion Laboratory, California Institute of Technology, Pasadena, CA 91109
(Dated: October 30, 2018)

Glitch Vetoing

Each point in these plots is a trial sky location to construct a network nullstream.



Analagous study for ET under way (Goncharov, Nitz).

Nullstream and CBC Parameter Estimation

Null-stream-based Bayesian Unmodeled Framework to Probe Generic Gravitational-wave Polarizations

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What if a relatively weak glitch perturbs a GW signal? Can you faithfully subtract it without nullstream? If not, how would such a glitch PE?

Explicitly shown in Wong et al,
nullstream does not help for CBC PE
if noise is Gaussian.

Stochastic GW Searches

Auto-correlation

$$\rho = \sqrt{T} \left[\int_0^\infty df \frac{\mathcal{R}^2(f) S_h^2(f)}{P_n^2(f)} \right]^{1/2}$$

Requires estimate of instrument-noise PSD, which can be affected by calibration errors.

Cross-correlation

$$\rho = \sqrt{2T} \left[\int_{f_{\min}}^{f_{\max}} df \frac{\Gamma_{IJ}^2(f) S_h^2(f)}{P_{nI}(f) P_{nJ}(f)} \right]^{1/2}$$

GW cross-PSD typically significantly reduced across two different interferometers compared to the GW PSD.

Both stochastic searches are limited by instrument-noise correlations.

Sensitivity curves for searches for gravitational-wave backgrounds

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