

# LIGU

## Towards the next generation of transient gravitational wave searches

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Gravitational wave detection and its sources

### Credits: Shanika Galaudage



# Masses in the Stellar Graveyard





### Towards future gravitational wave observatories





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### The next generation of challenges: Einstein Telescope



Credits: Andreas Freise

We will see more signals for longer times





## Matched filtering (MF) for CBC searches

Several pipelines for short modelled searches: GstLAL, PyCBC, SPIIR, ...

MF := matching models (templates) to unknown signals





Overlapping signals!







## Old and new challenges: transient noise burst (glitches)

- Caused by instruments or environment (known or unknown)
- o Diminish scientific data available
- Hinder transient GW searches (mask and/or mimic)
- Novel glitches in future runs



Example of a blip glitch (left) and a intermediate-mass BBH (right) GW170817 masked by a glitch

Normalized amplitude







### Towards the next generation of transient gravitational wave searches

Can Machine Learning help us with the next challenges?

We focus in two problems:

1. Understand populations of glitches  $\rightarrow$  better inclusion and modeling



2. Beyond current searches: extract more information

Blips from L1 and H1 (O2) are abundant and simple

IMBH signals are similar to other glitches





### 1. Understanding populations of glitches

### What is the aim of this work?

Simulate transient noise burst (glitches) from LIGO detectors with Machine Learning

### Why more? We have so many!

Create an open-source interface for production:

- mock data challenges: Einstein Telescope
- improve classifiers: controled dataset → robust algorithms and more!

### How are we going to do it?

Generate glitches in time domain with Generative Adversarial Networks





### Data and pre-processing





### Generative Adversarial Networks



Network employed: CT-GAN (Wei, ICLR 2018)





### CT-GAN: GP + CT with Dropout

### Some intuition from the experiments:

- Gradient Penalty (GP): balances the loss of the discriminator and generator
- Consistency term (CT): regularizes the generator.
- Dropout: regularizes the discriminator.

Both terms tend to zero when the network is stable.







## Building a fake population of blips







## Metrics and hypothesis to avoid misgenerations

Define metric m

 $m(b_i, b_j) :=$  similarity between two signals  $b_i$  and  $b_j$ .  $m(B, b_j) := \mu(M_j) \pm \varepsilon(M_j)$  where  $M_j := \{m(b_i, b_j) \forall b_i \in B\}$ What metrics?

Similarity measures  $\rightarrow$  Wasserstein distance (W<sub>1</sub>), Match function ( $M_f$ ), Normalized cross-covariance (k)

**Assumption:** CT-GAN learnt the underlying population except certain anomalies

If b<sub>j</sub> is reliable blip, it will represent both real and fake populations → m(B<sub>real</sub>, b<sub>j</sub>) ≈ m(B<sub>fake</sub>, b<sub>j</sub>) ≈ 1.0
If b<sub>j</sub> is anomalous blip, it will not represent both real and fake populations → m(B<sub>real</sub>, b<sub>j</sub>) ≈ m(B<sub>fake</sub>, b<sub>j</sub>) ≈ 0

Hypothesis:  $m(B_{real}, b_j)$  and  $m(B_{fake}, b_j)$  are linearly correlated.





### Results







#### A practical example with gengli 0.2 0.0 Amplitude -0.2 Mantainer: Stefano Schmidt -0.4 -0.6import gengli -0.8 = gengli.glitch\_generator('L1') q -1.0250 0 g\_whithened = g.get\_raw\_glitch() 1e-23 g\_coloured\_ET = g.get\_glitch(4, 2 srate = 16384, psd = 'EinsteinTelescopeP1600143', 0 SNR = 10Amplitude -2 -4 Full example: plot\_glitch.py -6 -8





GitHub repository: https://git.ligo.org/melissa.lopez/gengli <sup>16</sup>



### Selecting reliable generations

Build initial data set (100 samples) to compute the confidence of the generated glitch



d<sub>w</sub> : Wasserstein distance d<sub>mm</sub> : Mis-match (1- match) d<sub>cc</sub> : Cross covariance (1 - k)

Percentile  $p \in [0.0, 1.0]$ If the generated glitch is in the percentile region it is accepted. Otherwise, it is dropped.

## Questions so far?

Credits: James Webb





### 2. Beyond current searches

### What is the aim of this work?

Improve the robustness of GW searches by analysing trigger pipelines with ML

### Why?

Intermediate-mass binary black holes are hard to detect CBC searches generate triggers → "free" information that we can use Similar ideas with cWB: Gayathri et al. (2020), Lopez et al. (2021)

### How are we going to do it?

Distinguish IMBH signals from glitches with GstLAL triggers from a *truncated* search



## Matched filtering (MF) for CBC searches

Several pipelines for short modelled searches: **GstLAL**, PyCBC, SPIIR, ...

MF := matching models (templates) to unknown signals









## A simulated GW through a CBC pipeline

 $\Delta t$ : time where trigger happened - time where GW signal is present in the noise



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## A blip through a CBC pipeline

 $\Delta t$ : time where trigger happened – time where glitch happened



Trigger  $\rightarrow$  template in template bank





### What does the pattern look like of SNR against time?

Taking time interval: -1s < event time < 1s









## Simplest problem: binary classification with Gaussian Processes

**Task:** binary classification problem  $\rightarrow$  GW signal (IMBH) vs glitch class

To simplify the problem, we <u>discard time</u> component.

For a single event we have multiple triggers:  $(m_1, m_2, s_{1z}, s_{2z}, \chi^2, SNR)_i$  where  $i \in triggers \rightarrow \mu(m_1, m_2, s_{1z}, s_{2z}, \chi^2, SNR)$ 

where  $\chi^2 \rightarrow$  signal consistency check of time-frequency evolution of the signal SNR  $\rightarrow$  match between signal and template

To simplify the problem, we <u>balance the data set</u> with undersampling.

Number of samples glitch class = number of samples IMBH









## Simplest problem: binary classification with Gaussian Processes

### **Proof-of-concept:**

- Feature vector:  $[\mu(SNR), \mu(\chi^2), \mu(m_1), \mu(m_2), \mu(s_{1z}), \mu(s_{2z})]$
- Task: binary classification problem with undersampling  $\rightarrow$  IMBH vs glitch class  $\frac{1}{0}$  Package: Scikit-learn
- Algorithm: Gaussian Process classifier with default values
- Package: Scikit-learn
- Output: probability of being a glitch





Proof-of-concept:
 O 3 a
 Feature Vector: [μ(στατ), μ(x]), μ(m1), μ(m2), μ(s1z), μ(s2z)]
 Task: binary classification problem with undersampling → IMBH vs glitch class
 Algorithm: Gaussian Process classifier with default values
 Package: Scikit-learn
 Output: probability of being a glitch









### Preliminary results





## Conclusions & future work

Challenge 1		o We can generate blip glitches.
		o Generated blips represent the real blip population.
		o Construct a full pipeline for glitch generation.
		Generalize to other types of glitches.
		• Application of artificial data set.
		<u>https://git.ligo.org/melissa.lopez/gengli</u>
	$\square$	
Challenge 2 -	0 0 0	Proof-of-concept binary classification
		At least a testing accuracy > 0.8
		Get more data!
	(	Include time component: ordering might be relevant





Nik hef

# Thank you for listening! Questions?