

GEMINI

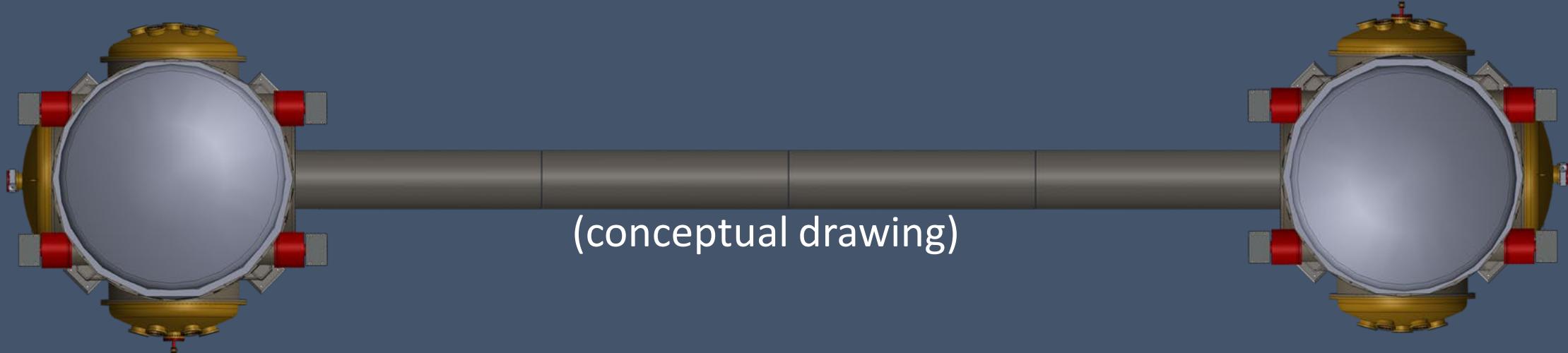
A new underground seismic-isolation facility at LNGS

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INFN - LNGS



- Two vacuum chambers connected by vacuum pipe
- Inertial platform inside each chamber
- Cryocooler and cold box for cryo-temperature payloads on one of the platforms

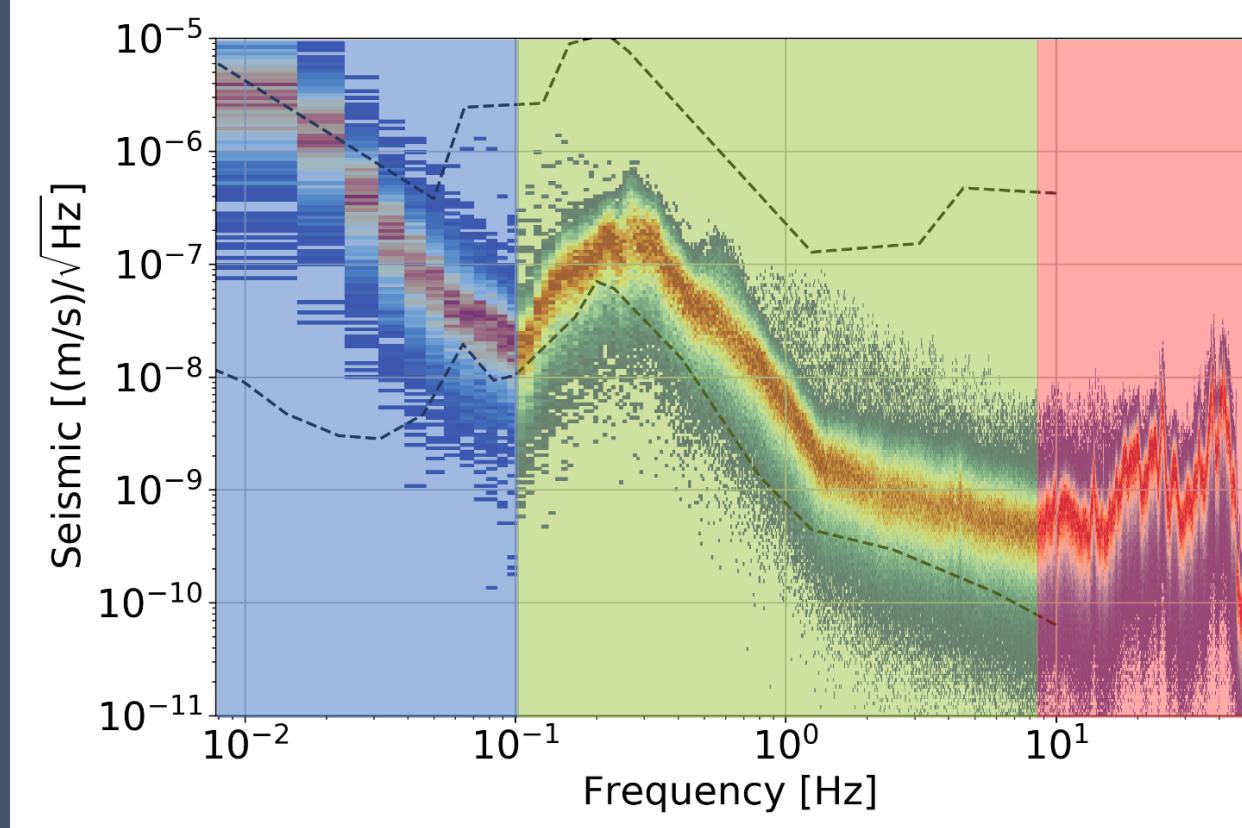
Background

- Experiment at INFN LNGS
- Collaboration between GSSI and LNGS
- Funded through two PNRR projects:
ETIC (80%) and ASTRA (20%)

Goals

- Test the limits of active seismic isolation in an underground environment
- Inter-platform motion control
- Underground environmental monitoring
- Test new approaches to controls optimization
- Test new inertial sensors

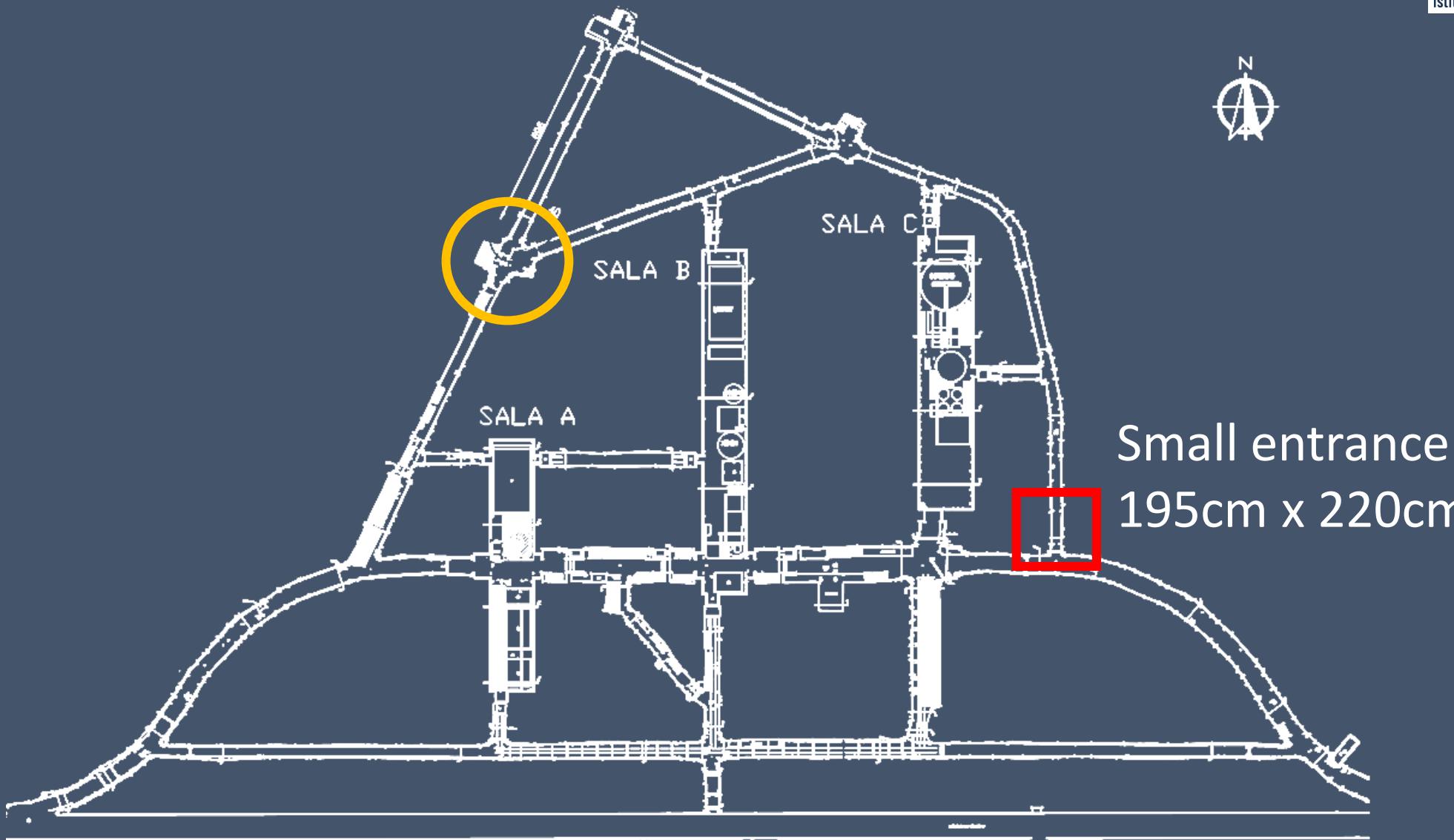
Underground Environment



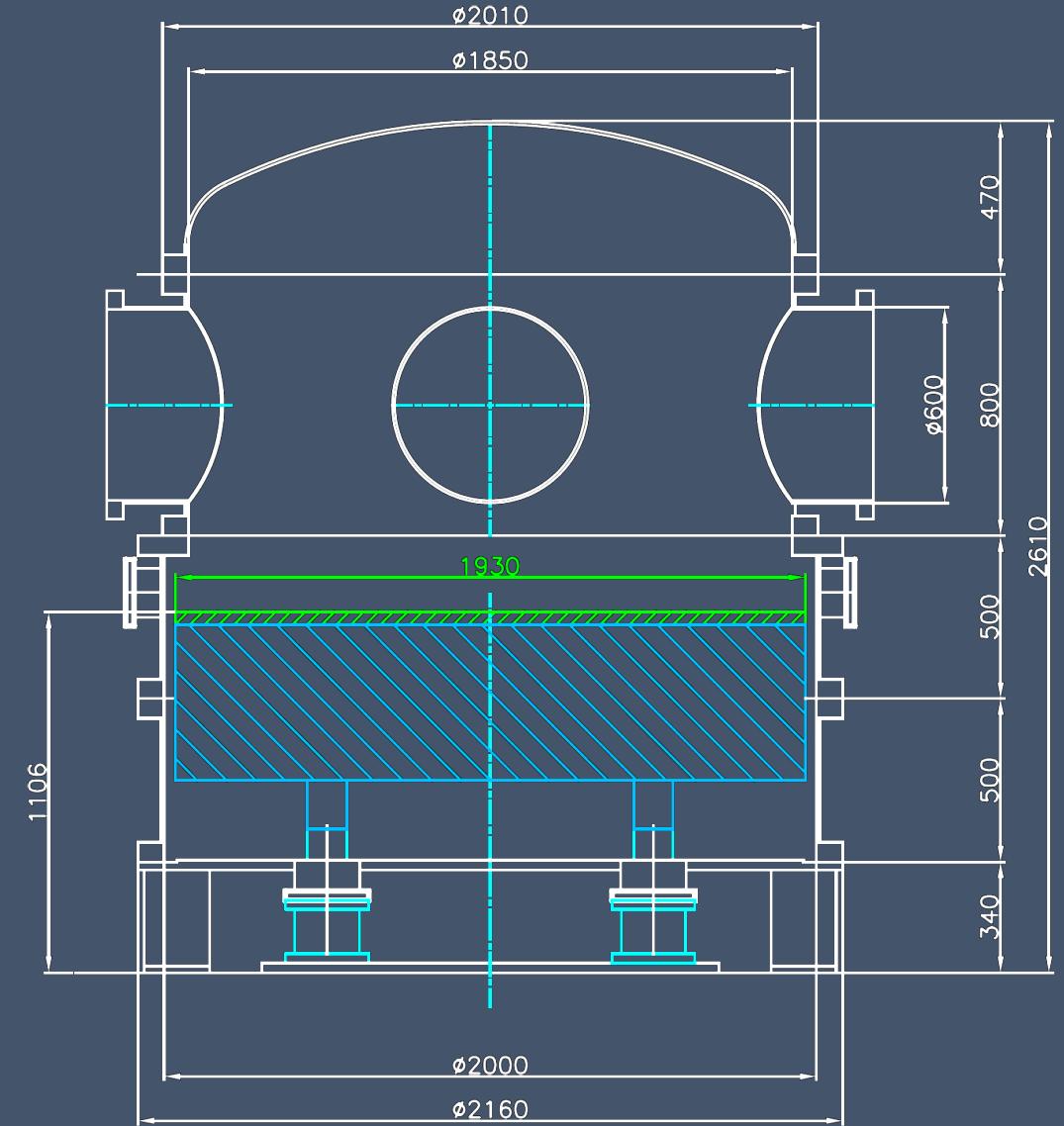
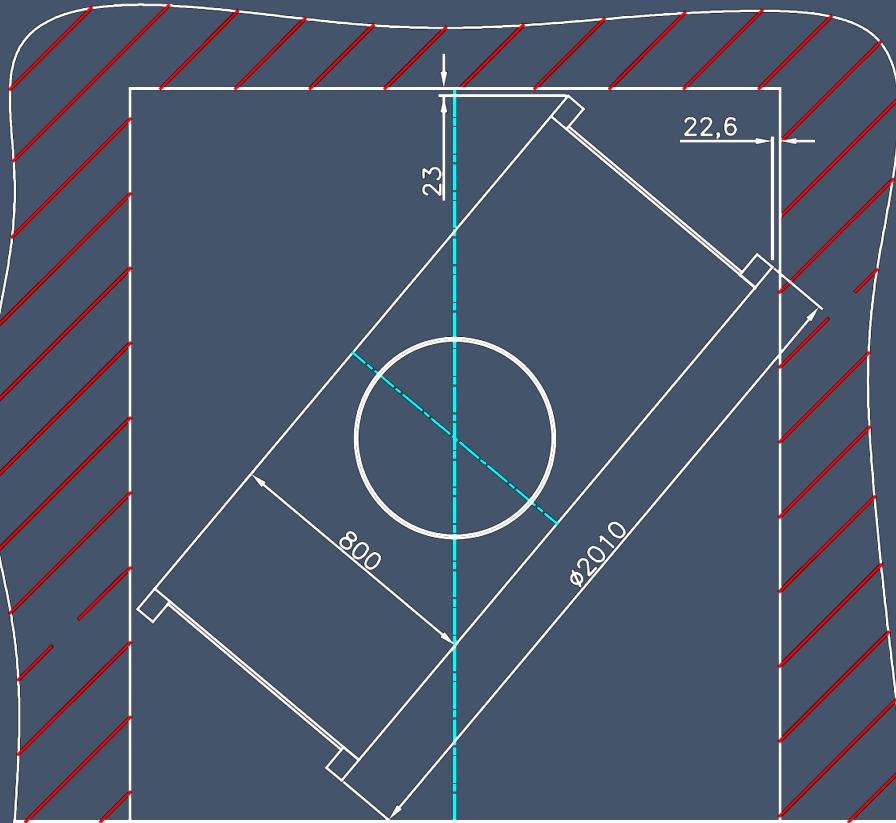
Blue: excess noise, which is probably ground tilt produced by pressure fluctuations
Green: natural low underground seismic noise
Red: excess noise from machines

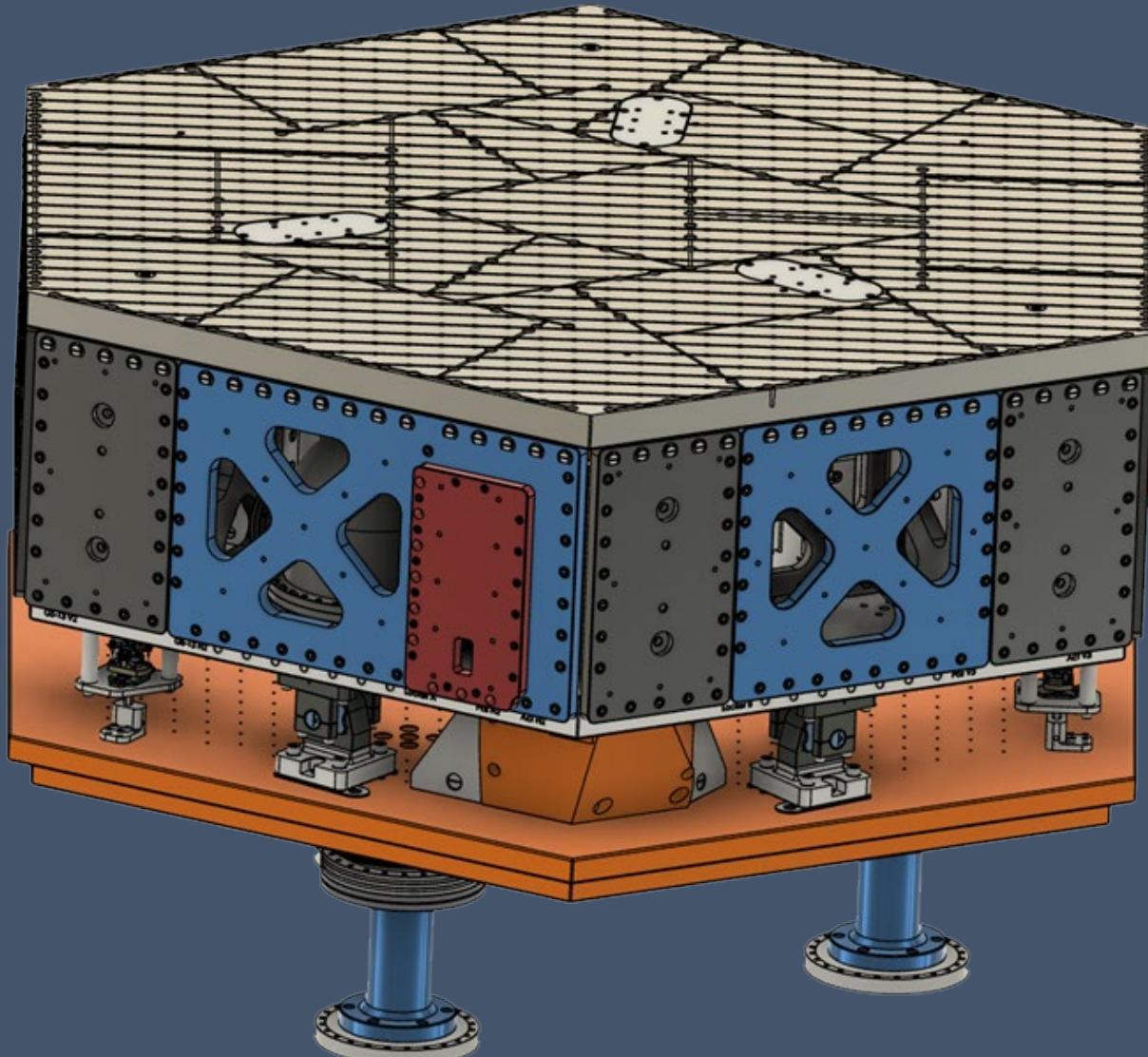
Important: Analyze <0.1Hz excess noise and its impact on active seismic isolation

GEMINI Site



Challenge: Installation



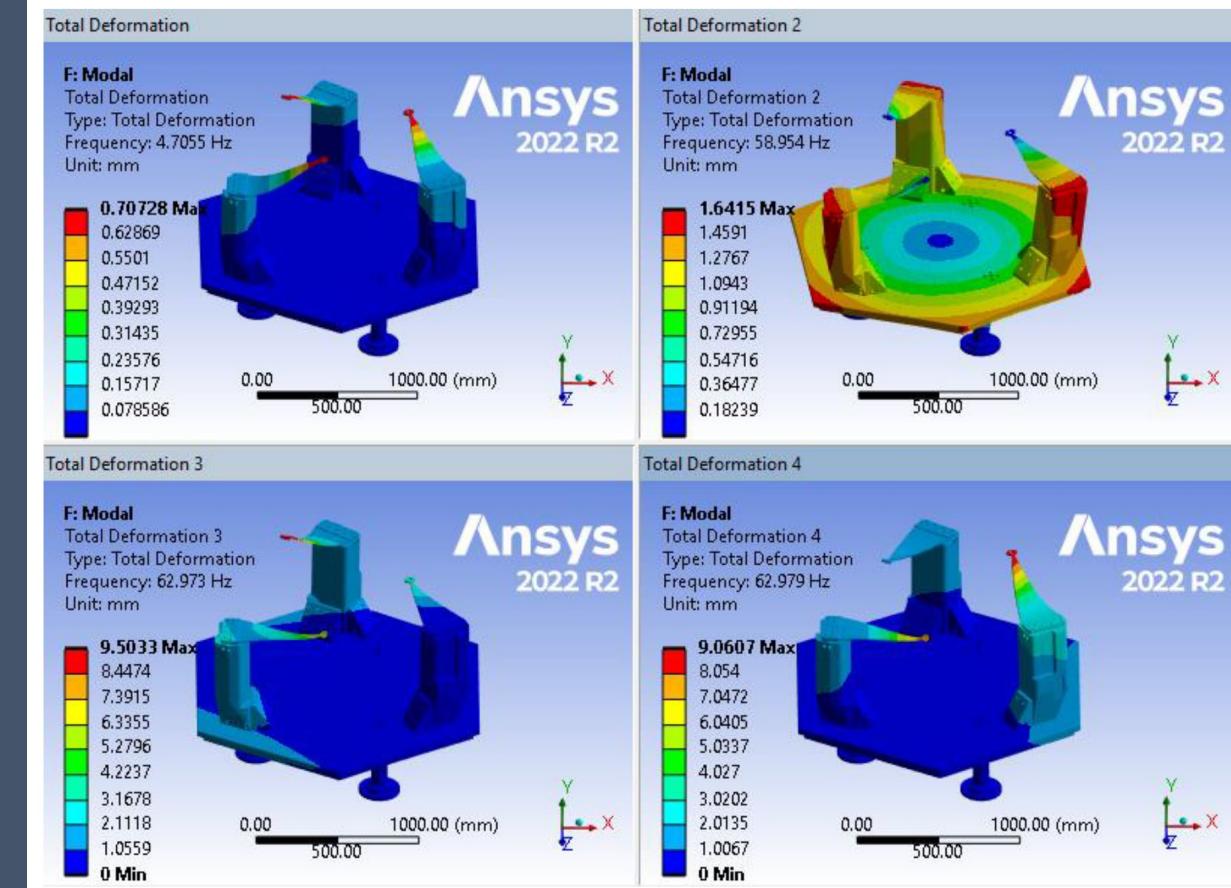
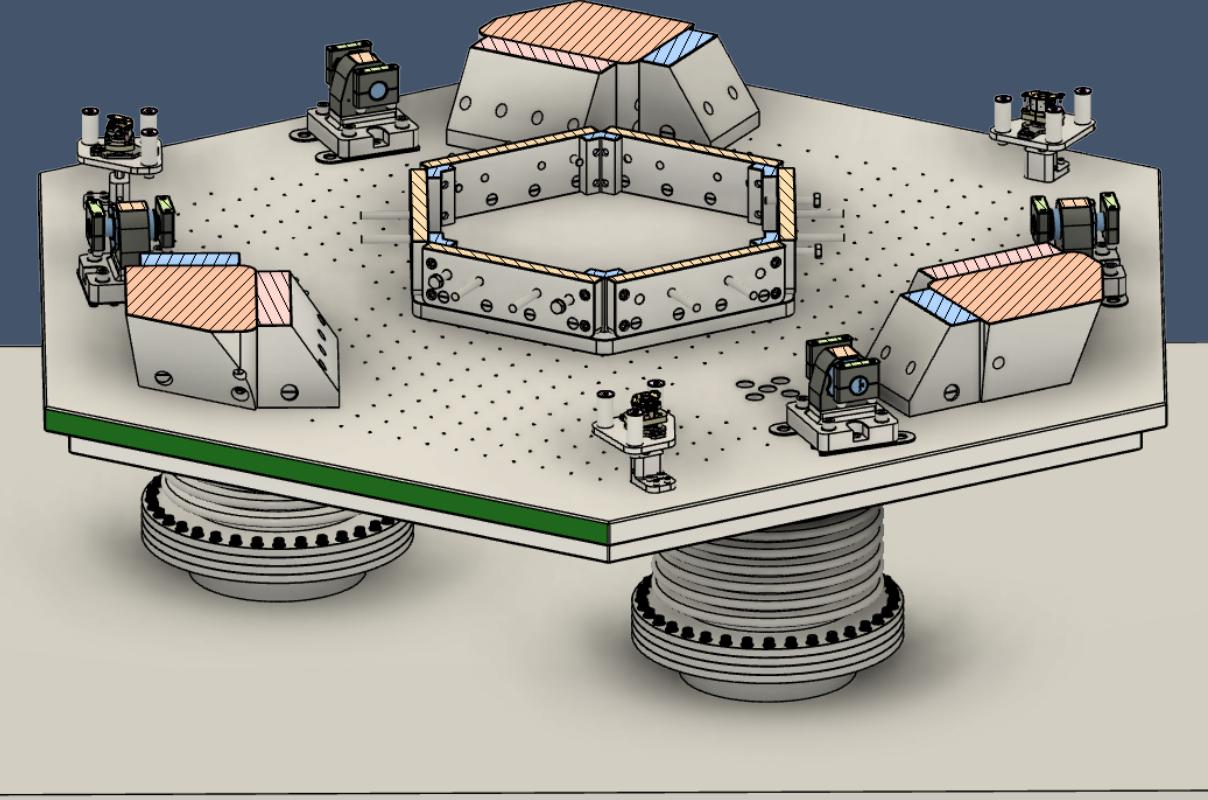


Adopted from LIGO HAM ISI:

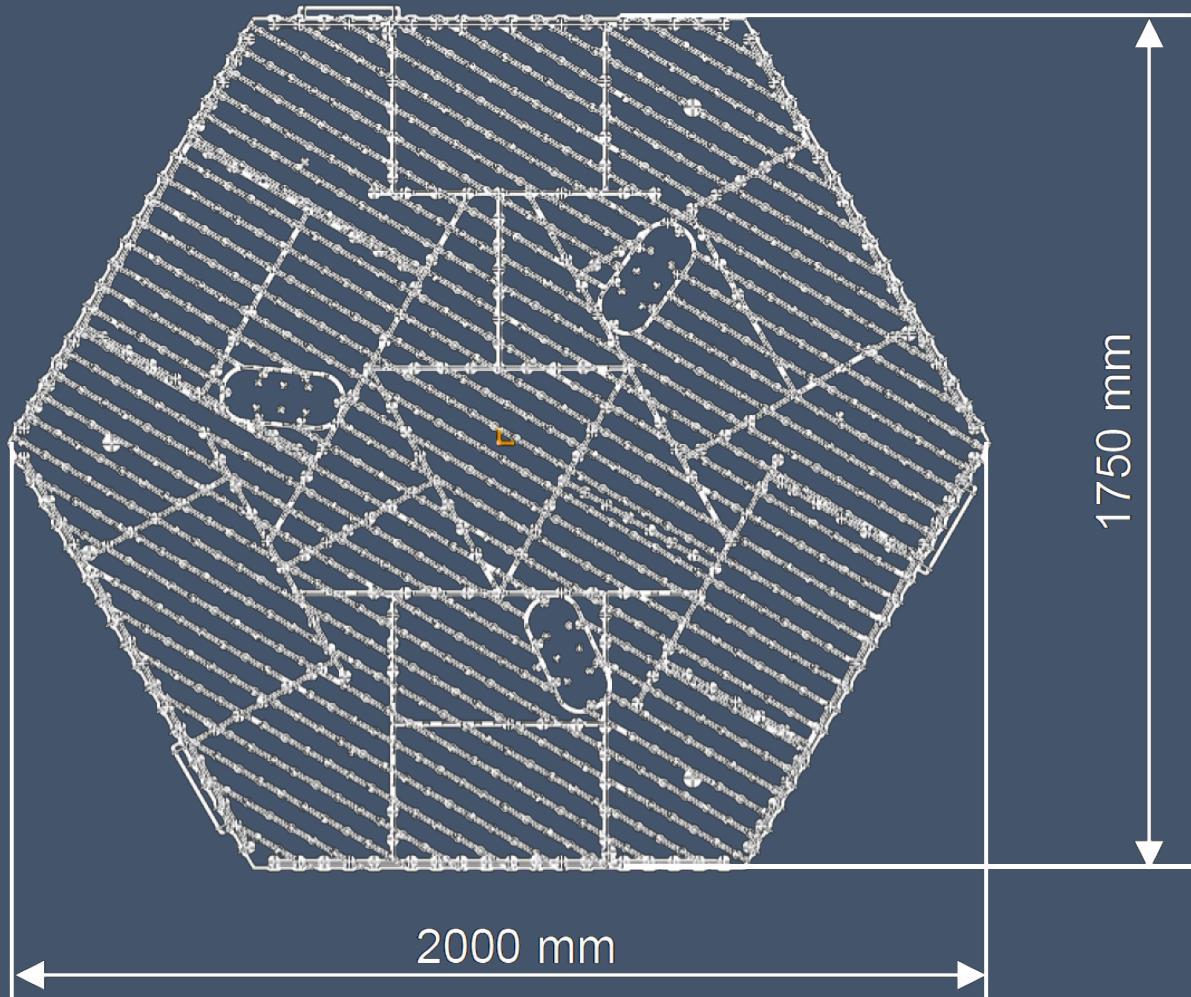
- Table edges cut
- Stage-1 sensors exchanged
(T360 GSN instead of GS-13)
- Major design modifications
of stage-0

GEM-IFI: Stage 0

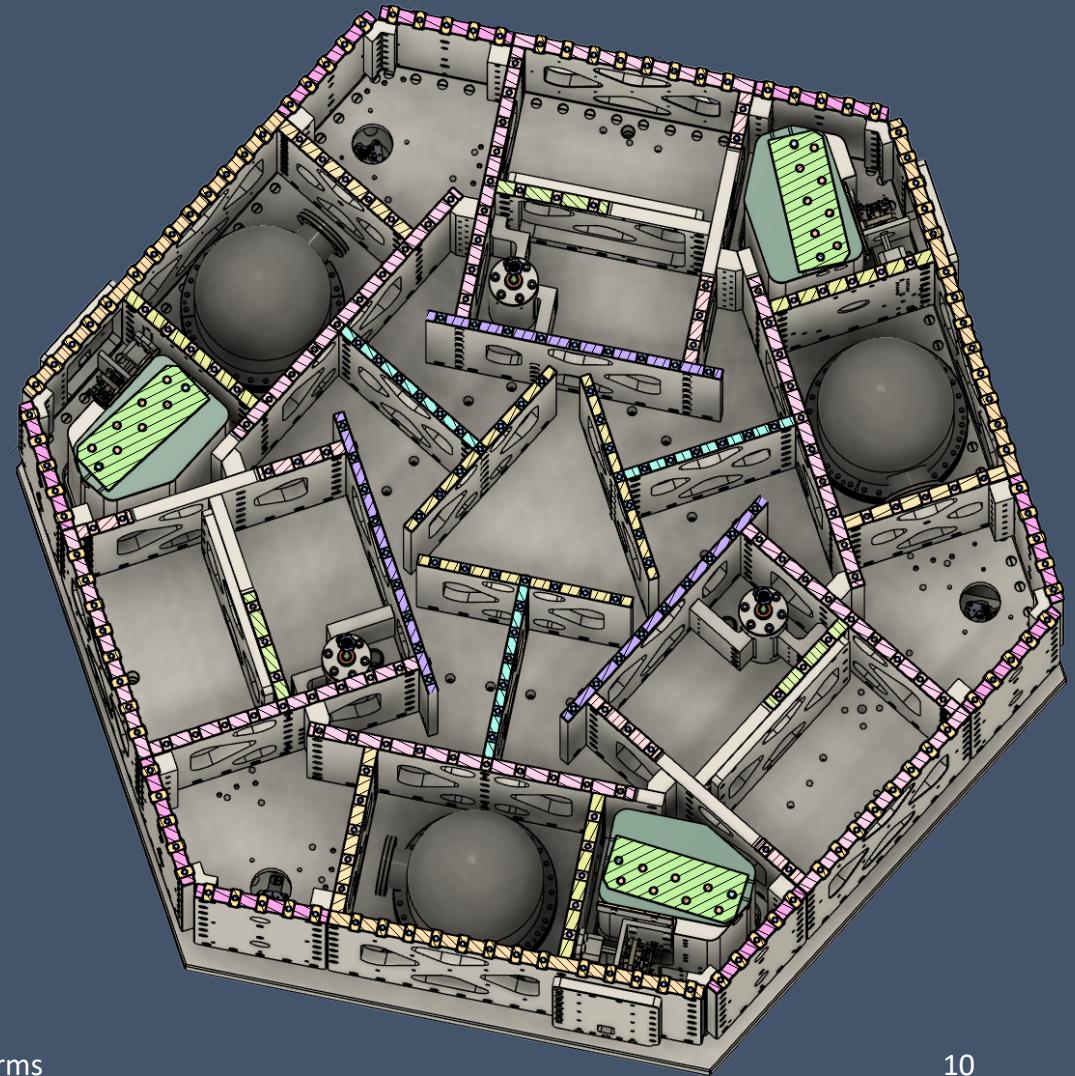
100Hz HAM-IFI (unconstrained)
70Hz GEM-IFI (under load)



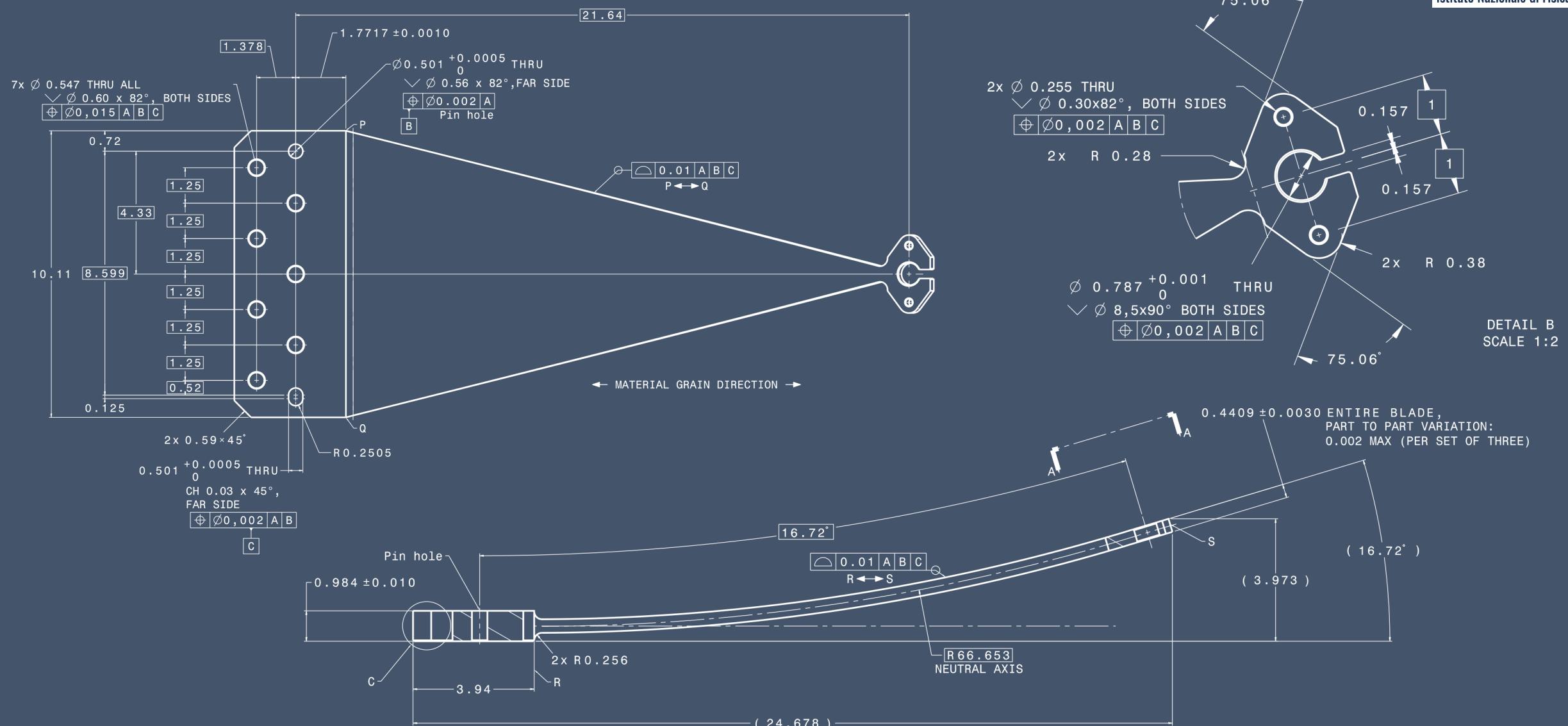
GEM-IFI: Stage 1



GEM-IFI like HAM-IFI (about 350Hz)

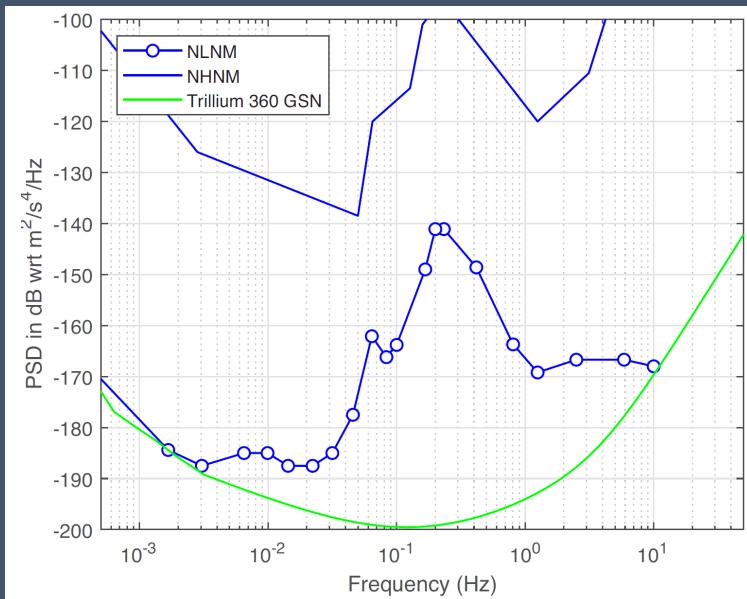


Maraging Steel Spring Blades

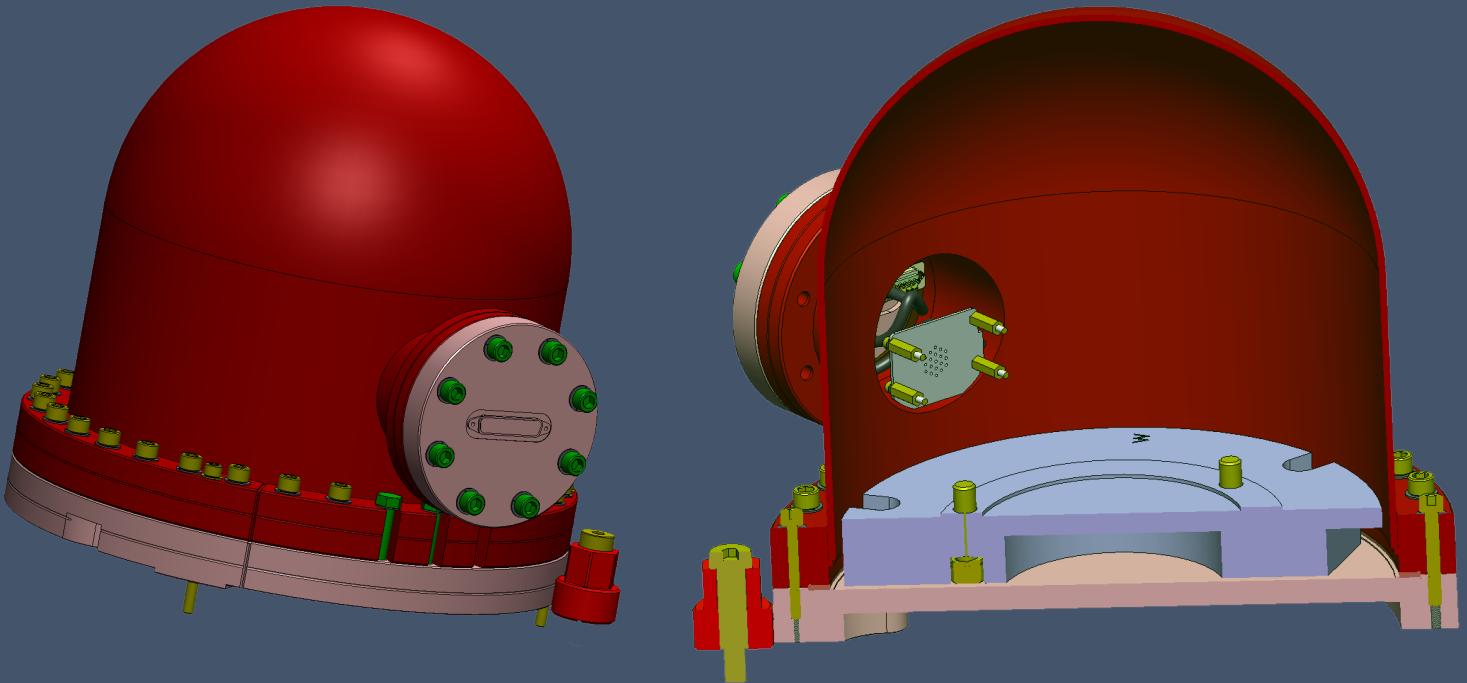


On-platform Seismometers

Nanometrics T360 GSN Vault

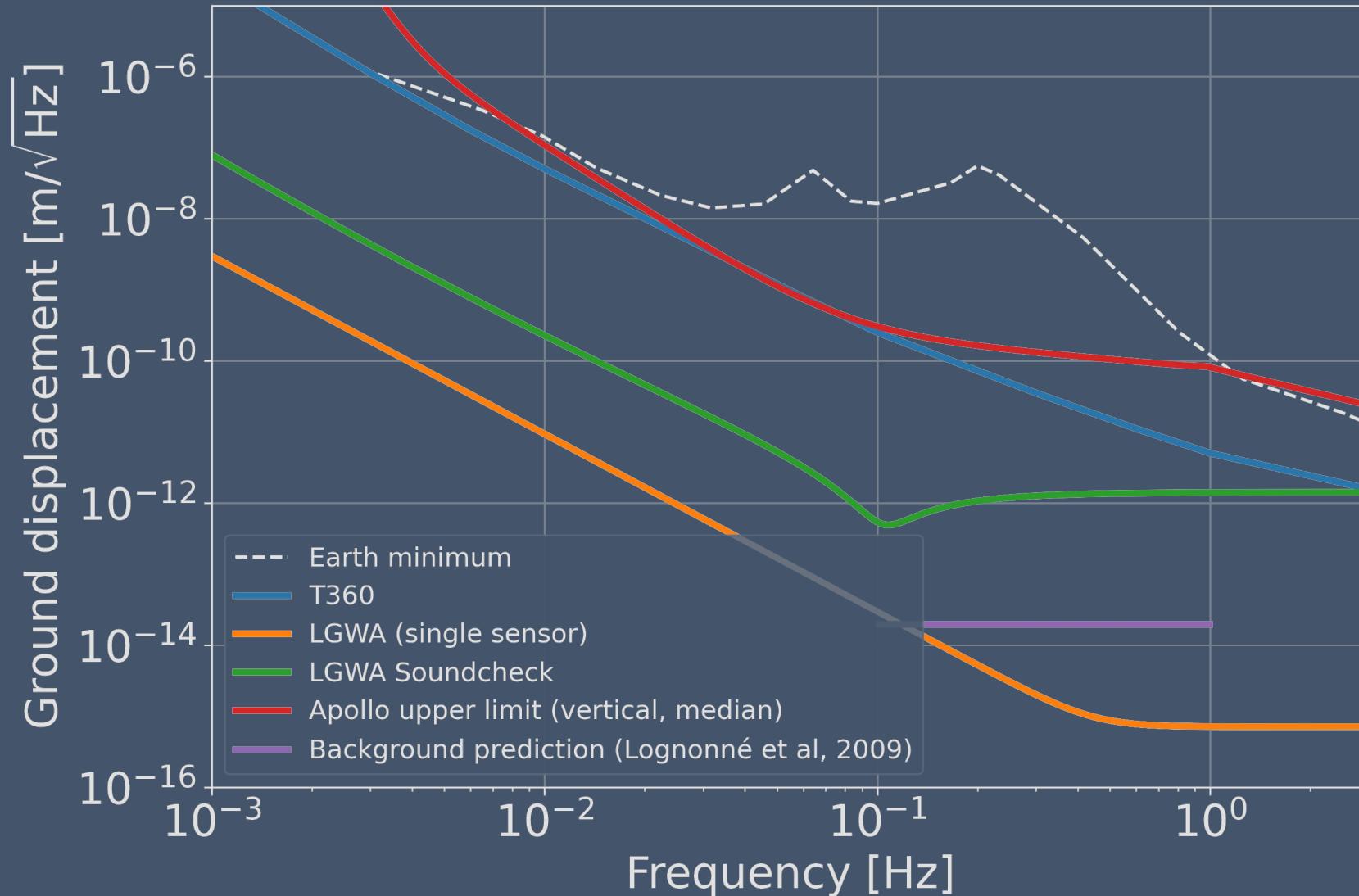


Vacuum pod



The T360 is not designed for in-vacuum operation, and a vacuum pod is required, which keeps a normal pressure.

Seismometer Test Bed



Missing Designs / Components

- Actuators and position sensors
(maybe something like BOSEM, but with updated coil actuator-design)
- Electronics (likely adopting updated CDS design)
- Cryocooler, cryolink and cryobox
- Barometer/microphone array (**not yet funded**)
- Inter-platform interferometer (**not yet funded**)
- Tiltsensor (**not yet funded**)