Atmospheric Newtonian noise modeling for third-generation gravitational-wave detectors

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Based on: Phys. Rev. D (2022) 106, 064040 Datasets: github.com/maurooi/AtmosphericNN More plots: 10.5281/zenodo.6758920.svg

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Motivations

Third-generation gravitational-wave (GW) detectors are expected to enhance the sensitivity of a factor ~ 10 and to push the frequency bandwidth down to 2-3 Hz

One of the major limitations in this region of the parameter space comes from Newtonian noise (NN)

NN is a fluctuation in the gravitational acceleration felt by the GW detector due to density perturbations in the nearby environment

Motivations

Two main NN contributions

Seismic: extensively studied in the past^[Saulson (1984)]_[Harms (2019)]

Atmospheric: modeled only for surface-based detectors in a simplified picture (homogeneous, isotropic, and frozen density perturbations)_[Creighton (2013)]

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Goal: improve the estimation of atmospheric NN by building more accurate and realistic models

Atmospheric NN is produced by temperature fluctuations δT generated by the heat of the sun and mixed by convection

Density perturbations $\delta \rho \propto \delta T$ produce a fluctuation in the gravitational acceleration δa

$$\delta \boldsymbol{a}(\boldsymbol{r},t) = \frac{G_N}{r^2} \delta \rho(\boldsymbol{r},t) \Delta V \,\hat{\boldsymbol{r}} = -\frac{\langle \rho \rangle}{\langle T \rangle} G(r) \delta T(\boldsymbol{r},t) \Delta V \,\hat{\boldsymbol{r}}$$

This has to be integrated over some volume of atmosphere and projected onto the detector arm, directed as \hat{n}_{arm} , giving

$$\delta a(t) = \int_{V} d^{3} \boldsymbol{r} \, \delta \boldsymbol{a}(\boldsymbol{r}, t) \cdot \boldsymbol{\hat{n}}_{arm}$$

The magnitude of the noise can be estimated statistically through its spectral density

$$S_{h}(\omega) \propto \omega^{-4} \int dt \, e^{i\omega t} \langle \delta a(t) \delta a(0) \rangle$$

$$\propto \omega^{-4} \int dt \, d^{3} \mathbf{r} \, d^{3} \mathbf{r}' G(r) G(r') \langle \delta T(\mathbf{r}, t) \delta T(\mathbf{r}', 0) \rangle$$

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Geometry

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Geometry Dynamics

Our models

We developed two distinct models to deal with atmospheric NN

Homogeneous and isotropic (HI): turbulence is homogeneously and isotropically distributed in the atmosphere

Inhomogeneous: we consider the inhomogeneities and anisotropies naturally present in atmospheric turbulence

In both models also include the effect of time correlations and decay of eddies

The key ingredient in our description is the choice of the correlation functions

We take the Fourier transform of $\langle \delta T(\mathbf{r}, t) \delta T(\mathbf{r}', t) \rangle$ $\langle \delta T(\mathbf{r}, t) \delta T(\mathbf{r}', t') \rangle \propto \int d^3 \mathbf{k} \, d\omega \, e^{-i\omega t + i\mathbf{k} \cdot (\mathbf{r} - \mathbf{r}')} \langle \delta T(\mathbf{k}, \omega) \delta T(0, 0) \rangle$

We factorize the spatial and temporal part of $\langle \delta T(k, \omega) \delta T(0, 0) \rangle$ $\langle \delta T(k, \omega) \delta T(0, 0) \rangle = f(k) h(\tau_k \omega)$

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	z ₀ [m]	Terrain	z ₀ [m]	Terrain
$z_0 = $ roughness	1	City	0.05	Farmland (open)
parameter	0.8	Forest	0.008	Mown grass
	0.2	Bushes	0.005	Bare soil (smooth)

Results — frozen HI

From HI turbulence in the frozen limit, we can understand the general features of the noise curves, which

- Decrease with f
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If the detector is located near the surface ($r_0 < 5 - 10$ m): **noise larger than the sensitivity!**



Results — decaying HI

 $\mathcal{E} = energy dissipation rate per unit mass$

Frozen contribution is dominant at small frequencies and depths

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Power spectrum scaling as $1/r_0^2$ Noise amplitude scaling as $1/r_0$



Results - Inhomogeneous

Again, frozen contribution is dominant at small frequencies and depths

Power law behavior at large f and r_0 Weak dependency on z_0 at small fand r_0

> Power spectrum scaling as $1/r_0^2$ Noise amplitude scaling as $1/r_0$



Conclusions

We improved previous models for the atmospheric contribution to NN by studying

- Time decay of turbulent structures
- Inhomogeneities along the vertical direction
- Dependency of NN from the detector depth

General features

- Noise is always suppressed at large frequencies
- Noise is partially mitigated placing the detector underground

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Thanks for your attention!

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Backup slides

Dependence on the wind angle



Dependence on roughness



Dependence on wind speed, Inhomogeneous



Dependence on cutoffs, Inhomogeneous



Explicit form of correlation functions, frozen HI

 \mathcal{E} = energy dissipation rate per unit mass \mathcal{E}_T = energy dissipation rate per unit mass per Kelvin

In the wind reference frame:

$$\langle \delta T(\boldsymbol{r},t) \delta T(\boldsymbol{r}',0) \rangle_{U} = \frac{\mathcal{C}_{K} \mathcal{E}_{T}}{(2\pi)^{3} \mathcal{E}^{\frac{1}{3}}} \int d^{3}\boldsymbol{k} \, d\omega \, k^{-\frac{11}{3}} \delta(\omega - \boldsymbol{k} \cdot \boldsymbol{U}) e^{-i\omega t + i\boldsymbol{k} \cdot (\boldsymbol{r} - \boldsymbol{r}')}$$

Therefore:

$$f(k) = C_K \mathcal{E}_T \mathcal{E}^{-2/3} k^{-11/3}$$

$$h(\tau_k \omega) = 2\pi \delta(\omega - \mathbf{k} \cdot \mathbf{U})$$

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$$f(k) = \mathcal{C}_K \mathcal{E}_T \mathcal{E}^{-2/3} k^{-11/3}$$
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