

Challenges in Newtonian noise estimations: rheological effects

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AHEAD 2020 workshop on the synergies between astrophysics and
geoscience

04–05 March, 2024

Common work with:



Tamás FÜLÖP



Róbert KOVÁCS

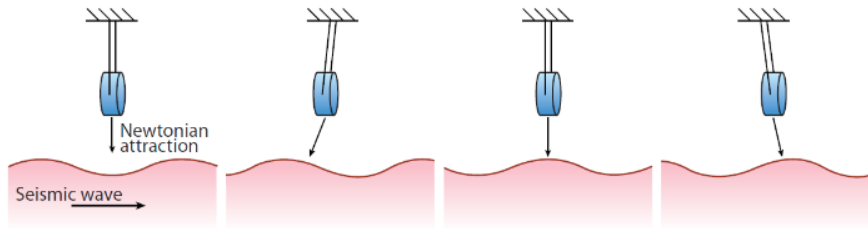


Péter VÁN

Detection of gravitational waves is based on displacement measurement \implies **Knowledge and separation of the motion of the surrounding environment and filtering and mitigation of noises are essential**

Several sources of noise (*e.g.*, standard quantum noise, thermal noise, scattering by residual gas), now we focus on:

- ▶ **Seismic noise:** persistent vibration of the ground, usually calculated via **elastic** models
- ▶ **Newtonian noise:** attraction of masses of nearby moving objects \implies direct coupling with seismic noises



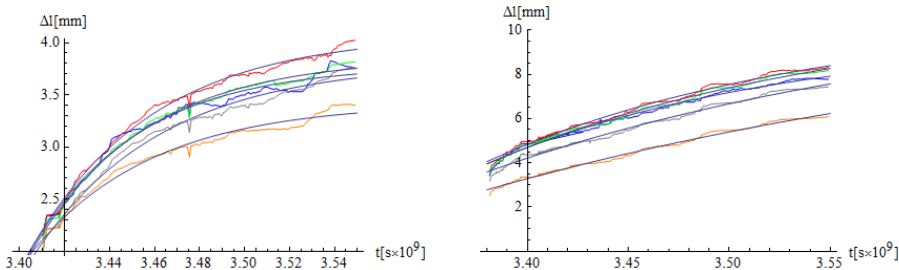
Soil and rocks are not so elastic as we expect

Tunnel squeezing: significant floor heave and wall closure



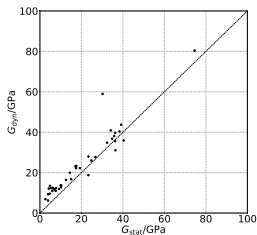
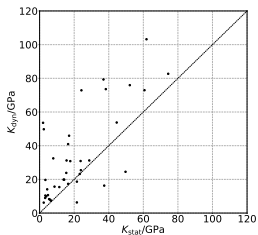
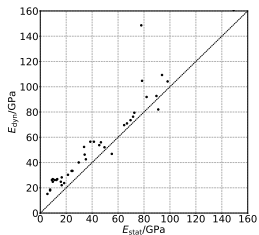
Basnet *et al.*: Analysis of squeezing phenomenon in the headrace tunnel of Chameliya Project, Nepal, *Hydro Nepal Journal of Water Energy and Environment* (2013)

Measured (and fitted) exponential-like displacement history of tunnel walls at the National Radioactive Waste Repository, Bataapati, Hungary, with characteristic times of 3–10 years



Kovács *et al.*: Revision and extension of the Geotechnical Interpretation Report (*in Hungarian*), Report RHK-K-032/12 by RockStudy Ltd. stored at the repository RHK Kft. Irattára, Pécs–Paks (2012)

Static vs. dynamic moduli of elasticity



Davarpanah *et al.*: Investigation of the relationship between dynamic and static deformation moduli of rocks. *Geomech. Geophys. Geo-energ. Geo-resour.* 6, 29 (2020)

Barnaföldi *et al.*: First report of long term measurements of the MGGL laboratory in the Mátra mountain range. *Class. Quantum Grav.* 34, 114001 (2017)

Ván *et al.*: Long term measurements from the Mátra Gravitational and Geophysical Laboratory. *Eur. Phys. J. Spec. Top.* 228, 1693—1743 (2019)

Rheological (a.k.a. viscoelastic) material behaviour: the response on the external effect is delayed and damped

Outline:

- ▶ Kluitenberg–Verhás rheological model family
- ▶ Wave propagation: numerical solutions
- ▶ Experimental investigations of rheological parameters

Kluitenberg–Verhás rheological model family

- ▶ Assuming:
 - ▶ A reversible model (here: Hooke elasticity/Duhamel–Neumann thermoelasticity)
 - ▶ Additional state variable: a second-order symmetric tensorial internal variable
 - ▶ Additional stress contribution
- ▶ Second law of thermodynamics
- ▶ Linear Onsagerian equations \implies coupling between the strain and internal variable

\implies **Thermodynamical compatibility**

Asszonyi *et al.*: Distinguished rheological models for solids in the framework of a thermodynamical internal variable theory, *Contin. Mech. Thermodyn.*, 27, 971–986 (2015)

Elimination of the internal variable and assuming homogeneous and isotropic material \implies Kluitenberg–Verhás rheology:

$$\begin{aligned}\boldsymbol{\sigma}^{\text{dev}} + \tau^{\text{dev}} \dot{\boldsymbol{\sigma}}^{\text{dev}} &= E^{\text{dev}} \boldsymbol{\epsilon}^{\text{dev}} + \hat{E}^{\text{dev}} \dot{\boldsymbol{\epsilon}}^{\text{dev}} + \hat{\hat{E}}^{\text{dev}} \ddot{\boldsymbol{\epsilon}}^{\text{dev}}, \\ \boldsymbol{\sigma}^{\text{sph}} + \tau^{\text{sph}} \left(\dot{\boldsymbol{\sigma}}^{\text{sph}} + \alpha E^{\text{sph}} \dot{T} \right) &= \\ &= E^{\text{sph}} \left[\boldsymbol{\epsilon}^{\text{sph}} - \alpha (T - T_{\text{aux}}) \mathbf{1} \right] + \hat{E}^{\text{sph}} \dot{\boldsymbol{\epsilon}}^{\text{sph}} + \hat{\hat{E}}^{\text{sph}} \ddot{\boldsymbol{\epsilon}}^{\text{sph}}\end{aligned}$$

where

$$\begin{aligned}\boldsymbol{\sigma}^{\text{sph}} &= \frac{1}{3} (\text{tr} \boldsymbol{\sigma}) \mathbf{1}, & \boldsymbol{\sigma}^{\text{dev}} &= \boldsymbol{\sigma} - \boldsymbol{\sigma}^{\text{sph}}, \\ E^{\text{dev}} &= 2G, & E^{\text{sph}} &= 3K\end{aligned}$$

Special cases

Hooke's law of elasticity

$$\boldsymbol{\sigma}^{\text{dev}} = E^{\text{dev}} \boldsymbol{\varepsilon}^{\text{dev}}, \quad \boldsymbol{\sigma}^{\text{sph}} = E^{\text{sph}} \boldsymbol{\varepsilon}^{\text{sph}}$$

Duhamel–Neumann thermoelasticity

$$\boldsymbol{\sigma}^{\text{dev}} = E^{\text{dev}} \boldsymbol{\varepsilon}^{\text{dev}}, \quad \boldsymbol{\sigma}^{\text{sph}} = E^{\text{sph}} \left[\boldsymbol{\varepsilon}^{\text{sph}} - \alpha (T - T_{\text{aux}}) \mathbf{1} \right]$$

Kelvin–Voigt viscoelasticity

$$\boldsymbol{\sigma}^{\text{dev}} = E^{\text{dev}} \boldsymbol{\varepsilon}^{\text{dev}} + \hat{E}^{\text{dev}} \dot{\boldsymbol{\varepsilon}}^{\text{dev}}, \quad \boldsymbol{\sigma}^{\text{sph}} = E^{\text{sph}} \boldsymbol{\varepsilon}^{\text{sph}} + \hat{E}^{\text{sph}} \dot{\boldsymbol{\varepsilon}}^{\text{sph}}$$

Poynting–Thomson–Zener rheology

$$\begin{aligned} \boldsymbol{\sigma}^{\text{dev}} + \tau^{\text{dev}} \dot{\boldsymbol{\sigma}}^{\text{dev}} &= E^{\text{dev}} \boldsymbol{\varepsilon}^{\text{dev}} + \hat{E}^{\text{dev}} \dot{\boldsymbol{\varepsilon}}^{\text{dev}}, \\ \boldsymbol{\sigma}^{\text{sph}} + \tau^{\text{sph}} \dot{\boldsymbol{\sigma}}^{\text{sph}} &= E^{\text{sph}} \boldsymbol{\varepsilon}^{\text{sph}} + \hat{E}^{\text{sph}} \dot{\boldsymbol{\varepsilon}}^{\text{sph}} \end{aligned}$$

Introducing

► Index of damping:

$$\mathcal{D}^{\text{dev}} = \hat{E}^{\text{dev}} - \tau^{\text{dev}} E^{\text{dev}} \geq 0, \quad \mathcal{D}^{\text{sph}} = \hat{E}^{\text{sph}} - \tau^{\text{sph}} E^{\text{sph}} \geq 0$$

based on thermodynamic criteria, hence

$$E_{\text{dyn}}^{\text{dev}} = \frac{\hat{E}^{\text{dev}}}{\tau^{\text{dev}}} \geq E^{\text{dev}} \equiv E_{\text{stat}}^{\text{dev}}, \quad E_{\text{dyn}}^{\text{sph}} = \frac{\hat{E}^{\text{sph}}}{\tau^{\text{sph}}} \geq E^{\text{sph}} \equiv E_{\text{stat}}^{\text{sph}}$$

► Index of inertia:

$$\mathcal{I}^{\text{dev}} = \hat{E}^{\text{dev}} - \tau^{\text{dev}} \mathcal{D}^{\text{dev}}, \quad \mathcal{I}^{\text{sph}} = \hat{E}^{\text{sph}} - \tau^{\text{sph}} \mathcal{D}^{\text{sph}},$$

if $\mathcal{I} > 0$, possibility of material resonance, no known material yet

Dispersion of waves in a Poynting–Thomson–Zener medium

1 + 1D equations (equation of motion, kinematic equation and PTZ rheology)

$$\rho \dot{v} = \sigma', \quad \dot{\varepsilon} = v', \quad \tau \dot{\sigma} + \sigma = E\varepsilon + \hat{E}\dot{\varepsilon}$$

Assuming plane wave solutions

$$\begin{pmatrix} v \\ \varepsilon \\ \sigma \end{pmatrix} (t, x) = \begin{pmatrix} A_v \\ A_\varepsilon \\ A_\sigma \end{pmatrix} e^{-(-\text{Im}\omega)t} e^{ik(x - \frac{\text{Re}\omega}{k}t)}$$

the dispersion relation is

$$\omega^2 \frac{1 - i\tau\omega}{1 - i\frac{\hat{E}}{E}\omega} = \frac{E}{\rho} k^2$$

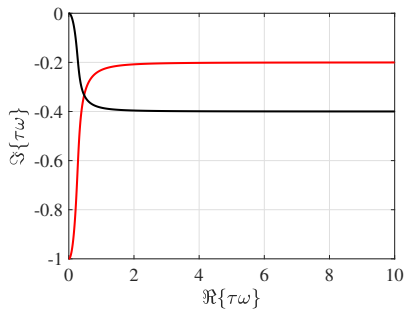
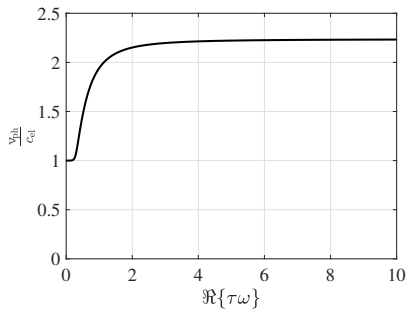
if $|\omega| \rightarrow 0$ (slow process):

if $|\omega| \rightarrow \infty$ (fast process):

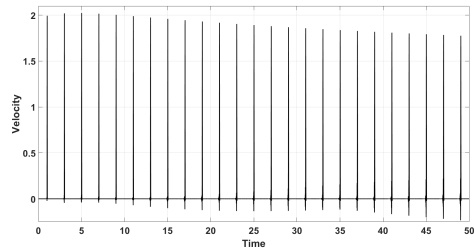
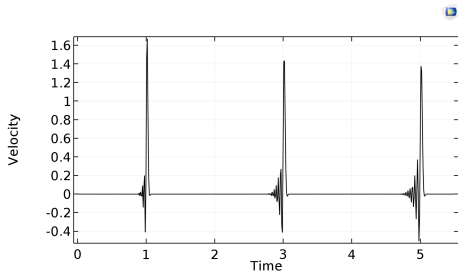
$$v_{\text{ph}} = \sqrt{\frac{E}{\rho}} = c_{\text{el}}$$

$$v_{\text{ph}} = \sqrt{\frac{\hat{E}_{\text{dyn}}}{\rho}} > c_{\text{el}}$$

Phase velocity and temporal attenuation, here $\frac{E_{\text{dyn}}}{E_{\text{stat}}} = 5$



Numerical solution of elastic wave propagation with COMSOL \implies reliability?



- ▶ Stability (numerical originated artificial exponential-like blow up)
- ▶ Dispersion error (numerical originated artificial oscillations)
- ▶ Dissipation error (numerical originated artificial increase/decrease of the amplitudes)

Our numerical method

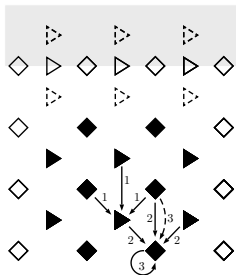
- ▶ Thermodynamical extension of a symplectic numerical scheme on a staggered space-time grid
- ▶ The discretized equations:

$$v_{n+1/2}^{j+1/2} = v_{n+1/2}^{j-1/2} + \frac{E}{\rho} \frac{\Delta t}{\Delta x} \left(\varepsilon_{n+1}^j - \varepsilon_n^j \right),$$

$$\varepsilon_n^{j+1} = \varepsilon_n^j + \frac{\Delta t}{\Delta x} \left(v_{n+1/2}^{j+1/2} - v_{n-1/2}^{j+1/2} \right),$$

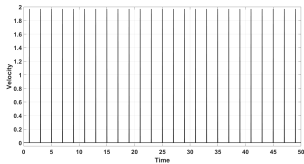
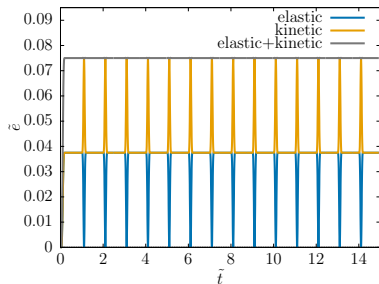
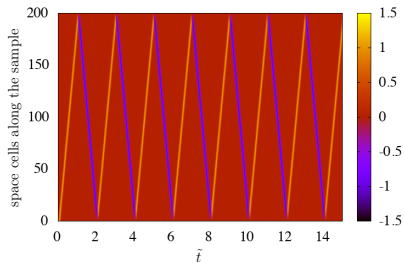
$$\sigma_n^{j+1} = \frac{1}{1 - \alpha + \frac{\tau}{\Delta t}} \left\{ \left(\frac{\tau}{\Delta t} - \alpha \right) \sigma_n^j + E \left[\alpha \varepsilon_n^j + (1 - \alpha) \varepsilon_n^{j+1} \right] + \hat{E} \frac{\varepsilon_n^{j+1} - \varepsilon_n^j}{\Delta t} \right\}$$

if $\alpha = \frac{1}{2}$ the scheme is second order accurate

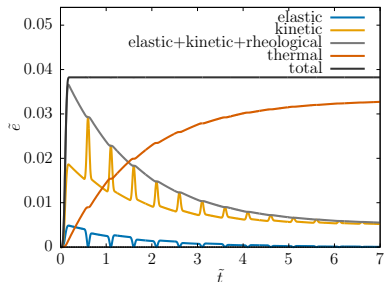
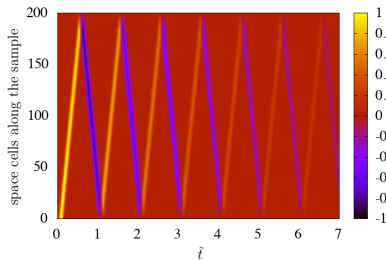


Fülöp *et al.*: Thermodynamical extension of a symplectic numerical scheme with half space and time shifts demonstrated on rheological waves in solids. *Entropy* 22, 155 (2020)

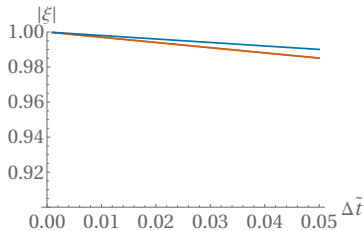
Numerical results: elastic wave propagation



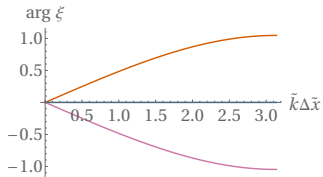
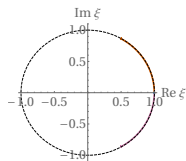
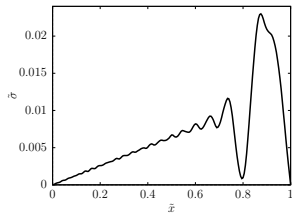
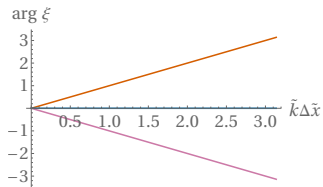
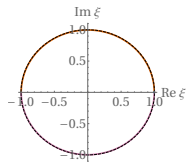
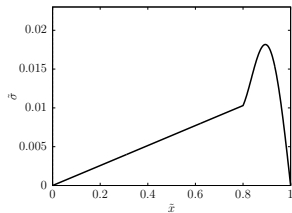
Numerical results: rheological wave propagation



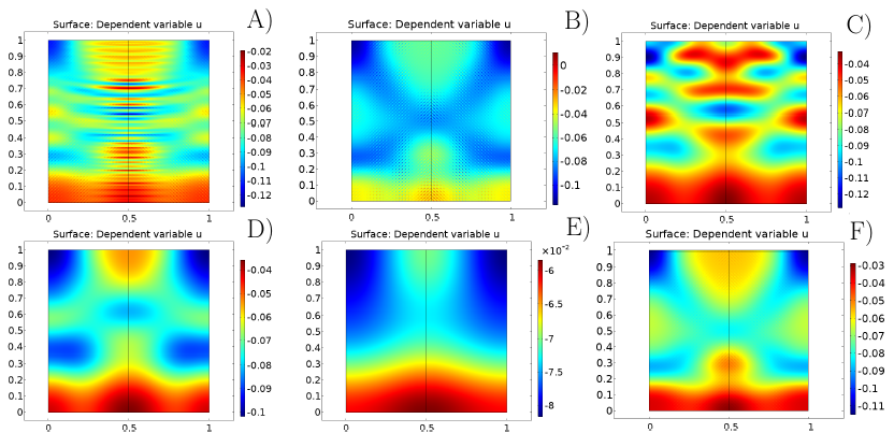
Dissipation error



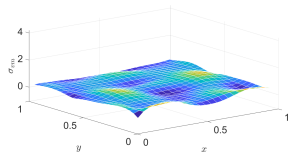
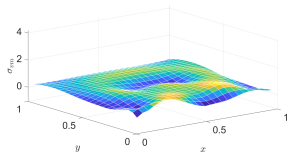
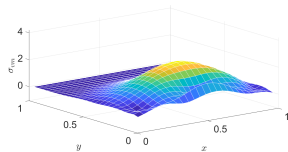
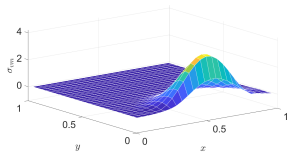
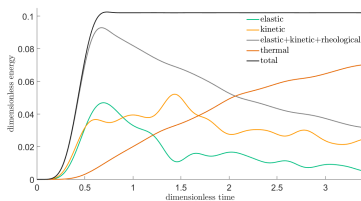
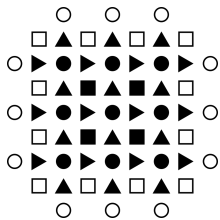
Dispersion error



COMSOL 2D scalar wave equation \implies reliability?



Generalization the self-developed scheme for 3 spatial dimensions



Pozsár *et al.*: Four spacetime dimensional simulation of rheological waves in solids and the merits of thermodynamics. *Entropy* 22, 1376 (2020)

Experimental investigations



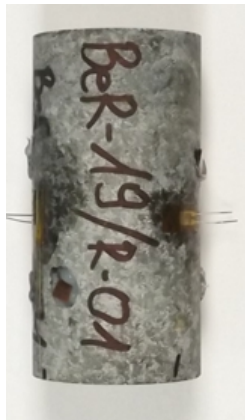
László KOVÁCS



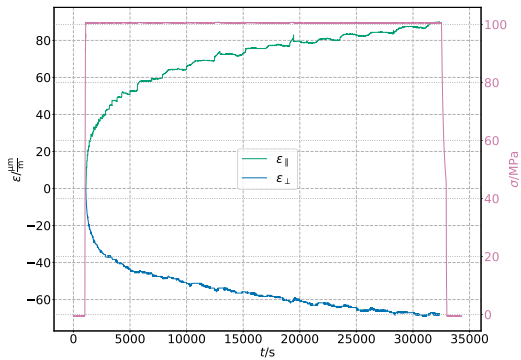
ROCKSTUDY

`kovacslaszlo@komer.hu`

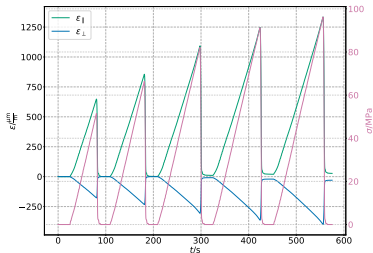
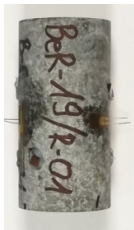
Measurement of creep: viscosities



Contaminated
monzonite

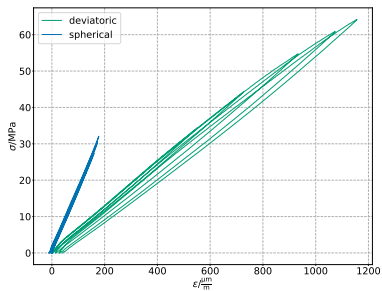
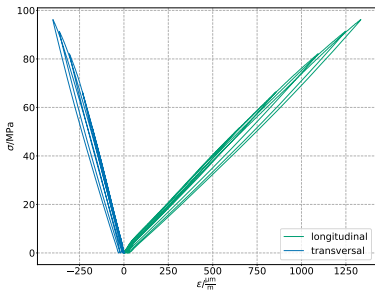


Measurement of hysteresis: time constants and beyond

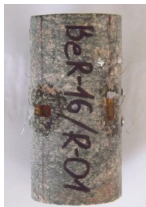


longitudinal-transversal

deviatoric-spherical

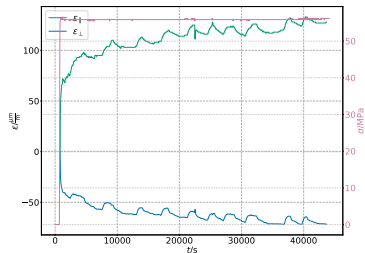


The effect of thermal expansion

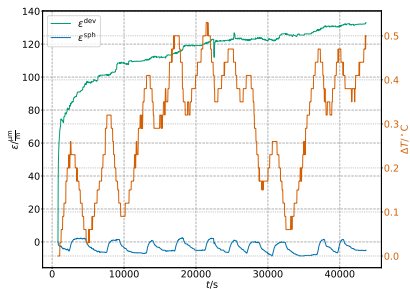
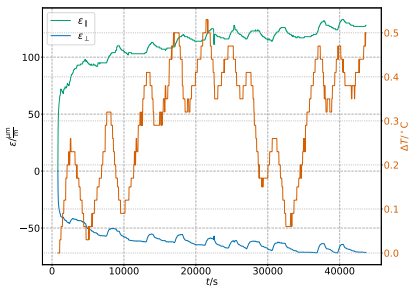


Reddish-gray hybrid
monzonite

longitudinal-transversal



deviatoric-spherical

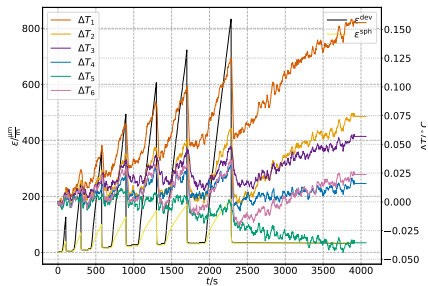
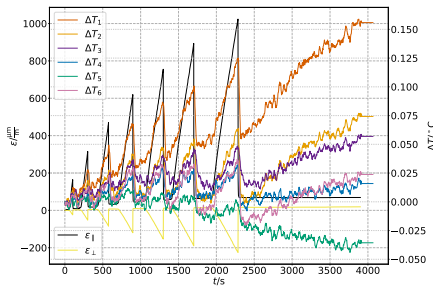
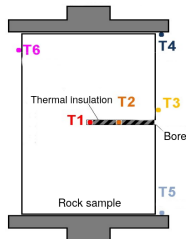


Temperature is space dependent

T1 ... T6: temperature sensors



Gray andesite



- ▶ Rheology of the surrounding rocks may notably affect the filtering and mitigation of Newtonian noise
- ▶ Advantage or disadvantage?
- ▶ Measurements of the rocks in the planned locations are required!

THANK YOU FOR YOUR KIND ATTENTION!